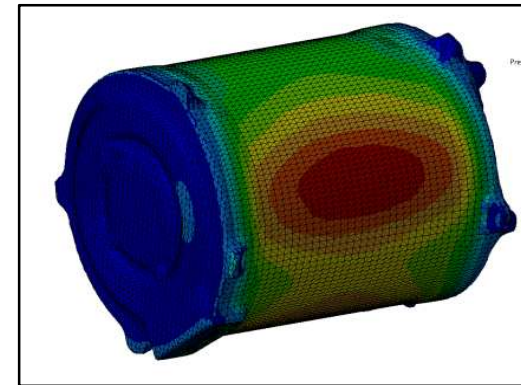
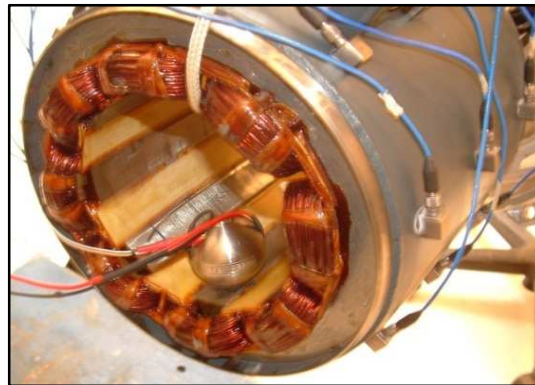
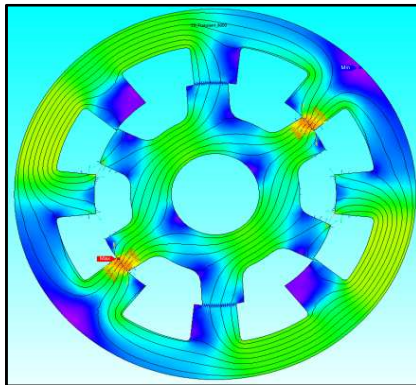


CAE Based Noise Optimization of a Switched Reluctance Electric Motor for Automotive Propulsion Applications



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Authors: Joris Van Herbruggen, Stefano Orlando, Jan Anthonis – LMS, a Siemens Business
Saphir Faid, Diederik Brems, Fabrice Boon – Punch Powertrain N.V

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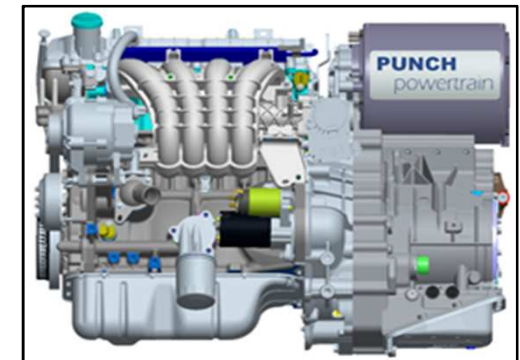
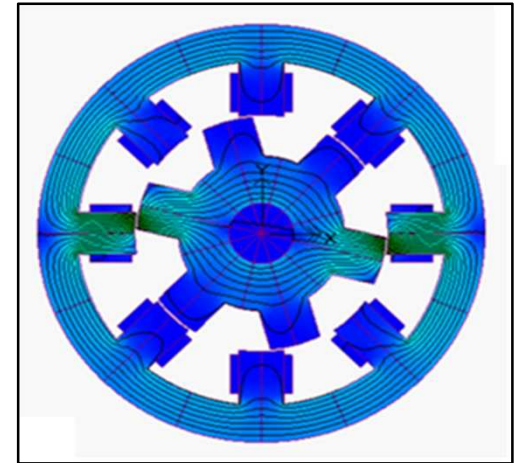


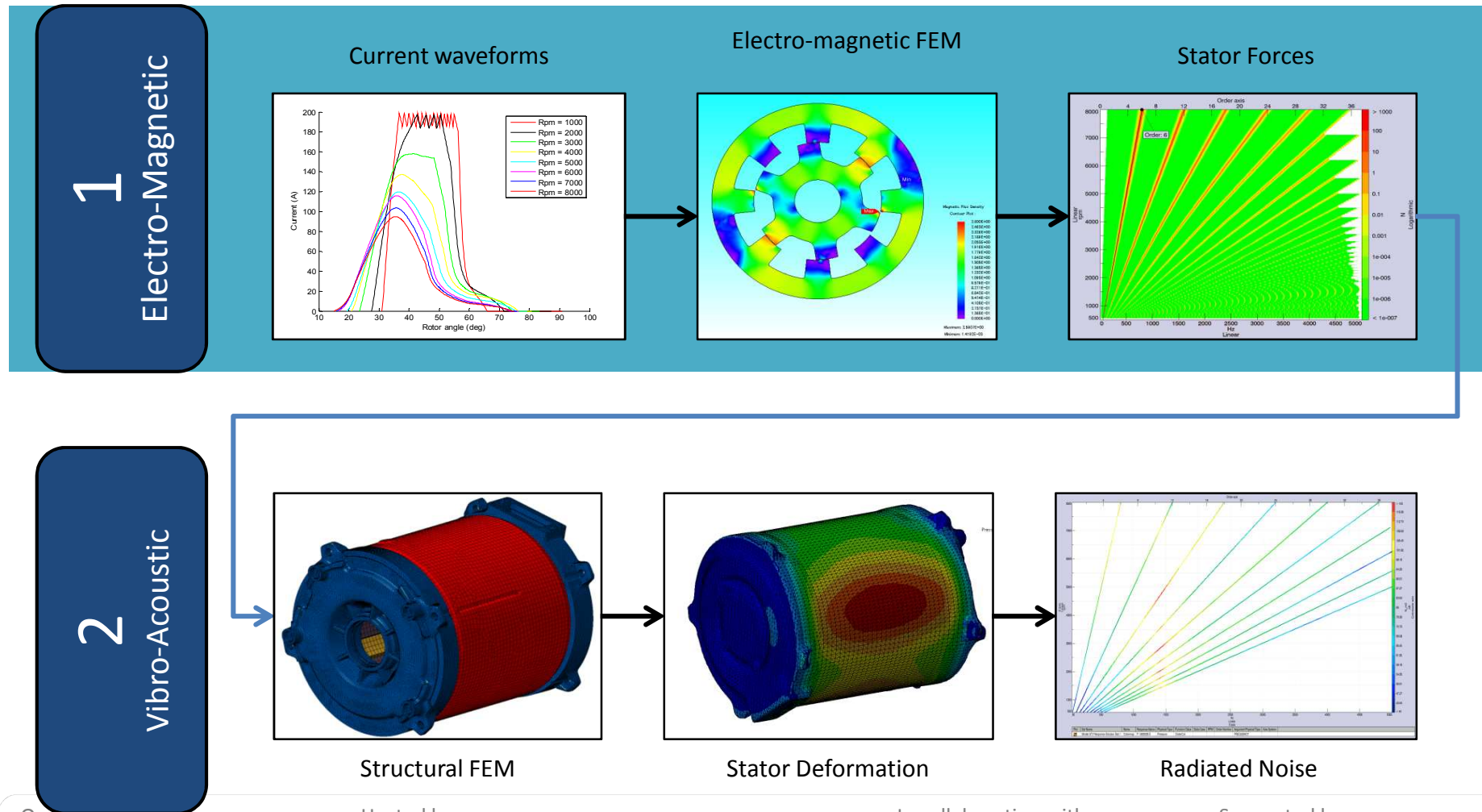
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- Electric motors are key to all electric and hybrid-electric automotive propulsion solutions.
- Main advantage of Switched Reluctance (SR) type electric motors
 - Cost-effective technology, simple construction
 - No rare-earth materials (permanent magnets)
 - No electric or magnetic components in rotor
- Main drawback in automotive applications
 - Control for maximum efficiency leads to high torque ripple
 - High torque ripple creates NVH problems.





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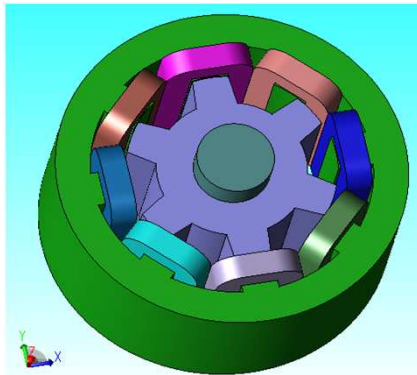
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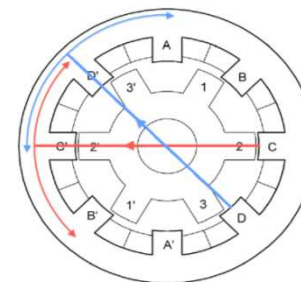
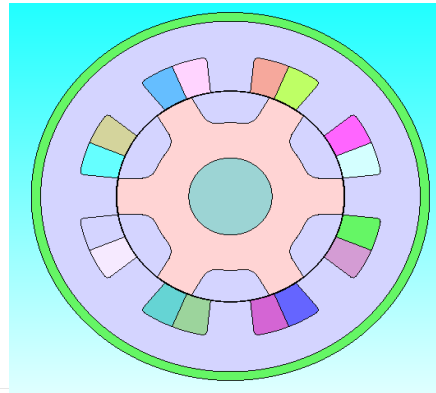
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- 2D Electro-Magnetic FE-model (stator, rotor, windings)
- Time domain simulation based on current waveforms for 60° rotor rotation
 - For motor and generator mode
 - For rpms from 525 rpm to 8.000 rpm
 - Only 60° of rotation are computed
 - Full 360° electro-magnetic FE modeled is calculated
 - Maximum frequency of interest: 5000 Hz (sampling frequency of 50000 Hz)
 - Minimum frequency for each rpm is the 6th order frequency

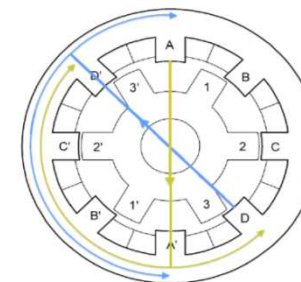
3D FE model



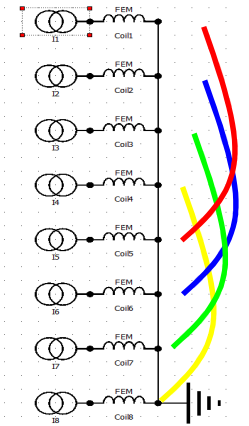
2D FE model



(a) Between stator poles C' and D'



(b) Between stator poles A' and D'



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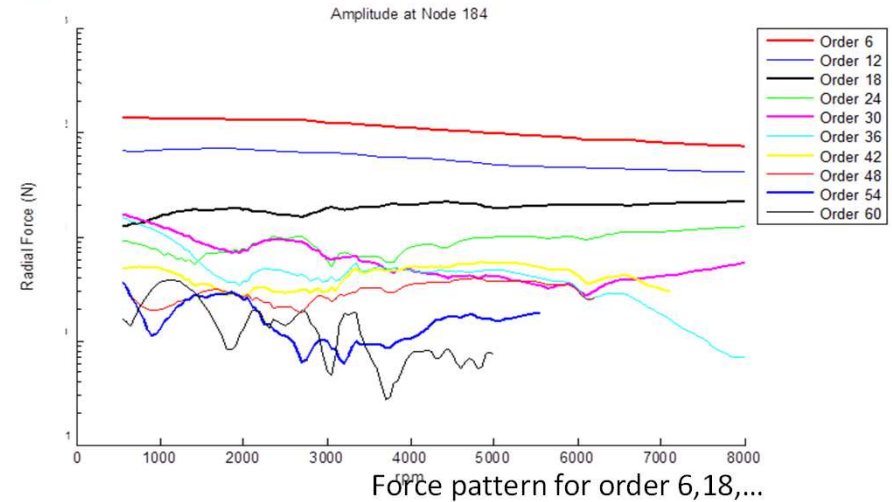


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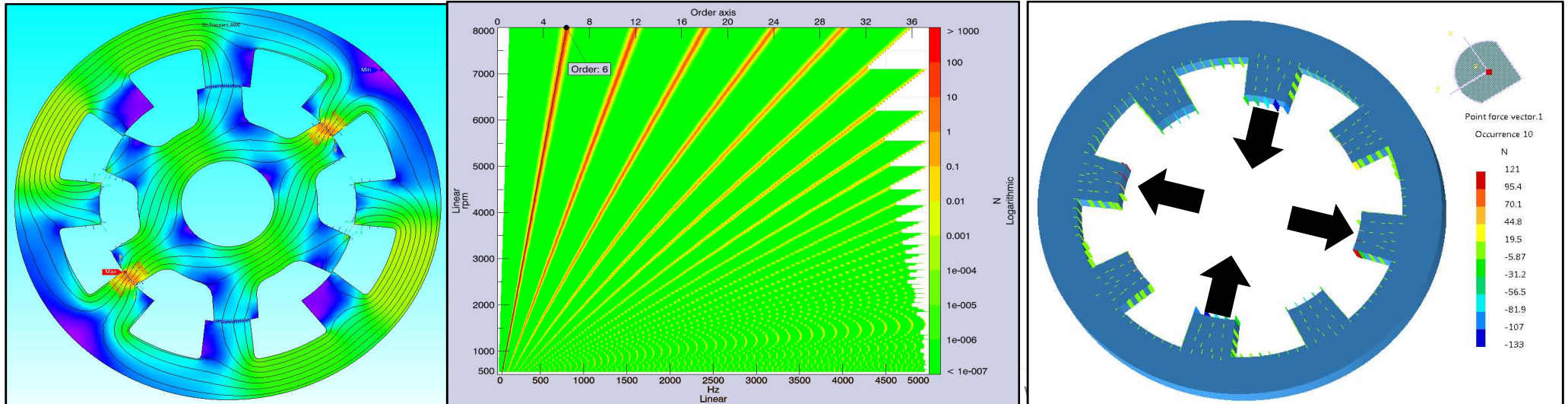
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- Results
 - High tangential forces between rotor and stator (motor torque)
 - Radial forces more likely to cause noise
 - The top orders have smooth, continuous lines



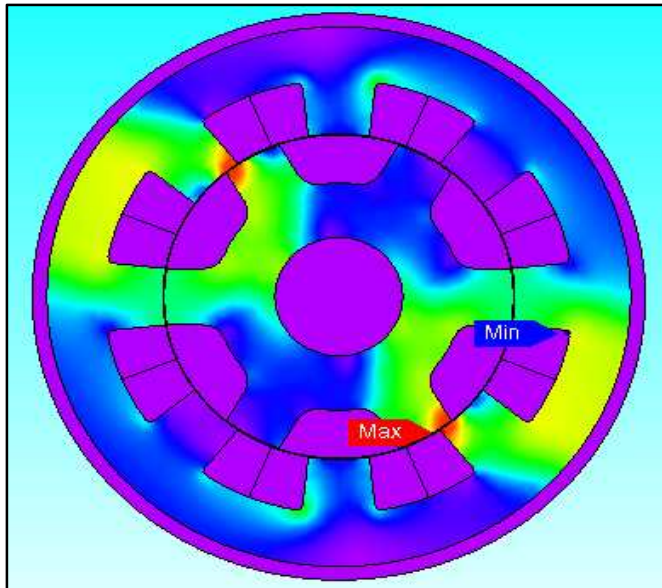
Magnetic flux lines

Stator forces

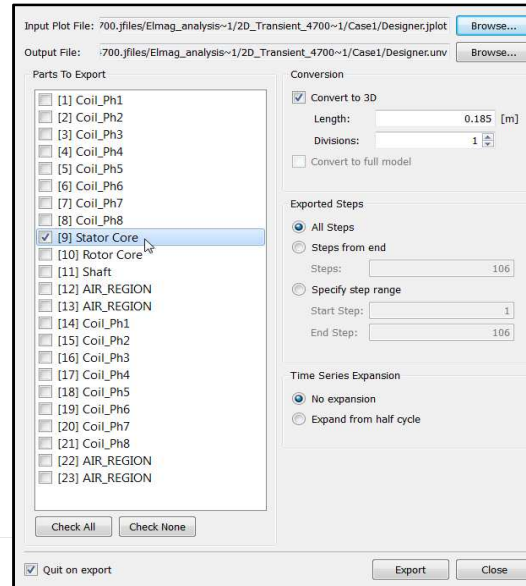


- JMAG: Export to VL functionality: Export of forces on stator surface in time domain and extrusion from 2D to 3D model
- LMS Virtual.Lab Acoustics:
 - Conservative mapping from EM mesh onto structural model mesh
 - Conversion from time to frequency domain

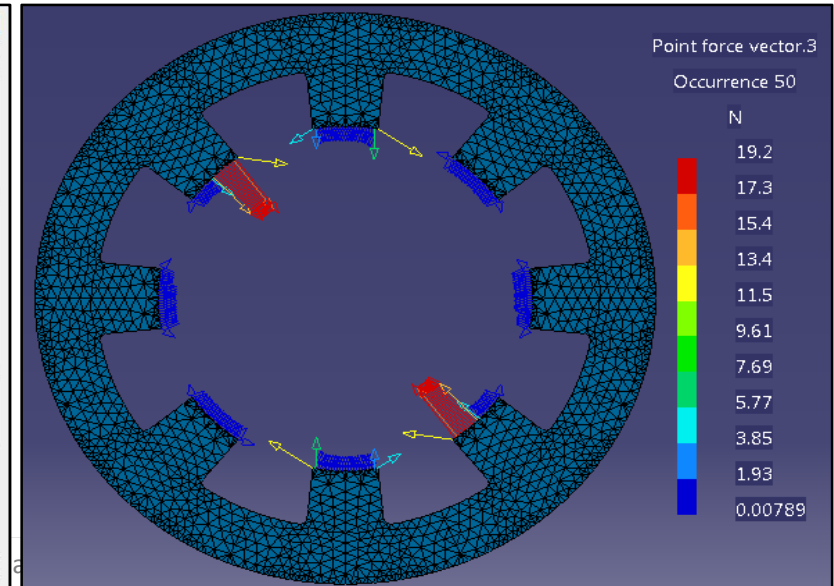
Magnetic Flux Density
in JMAG



Force Export to
LMS Virtual.Lab



Forces on SRM stator in
LMS Virtual.Lab

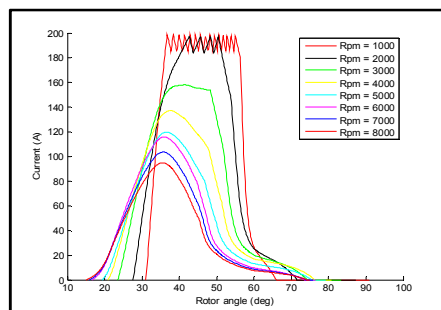


Noise optimization of an SR electric motor Overview

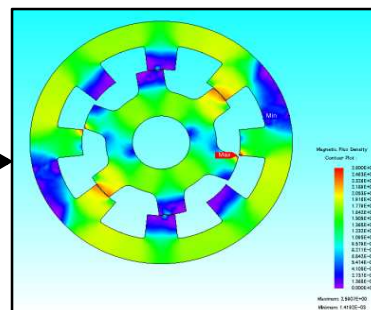
1

Electro-Magnetic

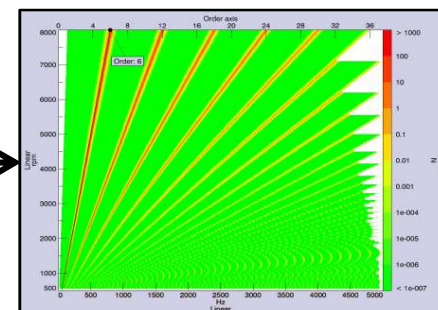
Current waveforms



Electro-magnetic FEM

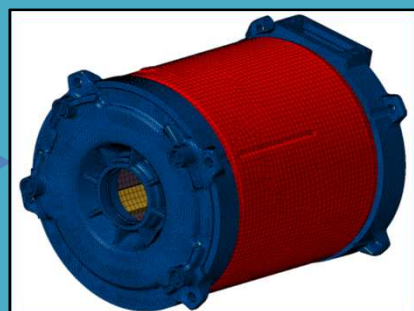


Stator Forces

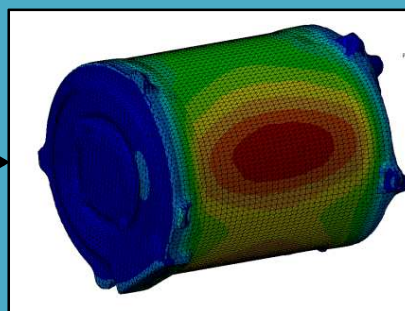


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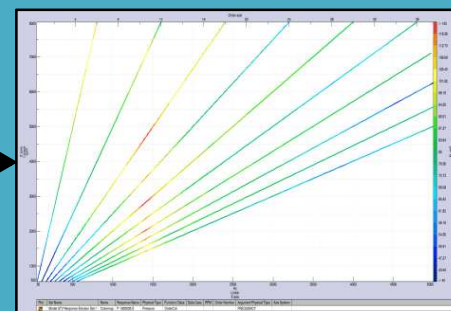
Vibro-Acoustic



Structural FEM



Stator Deformation



Radiated Noise

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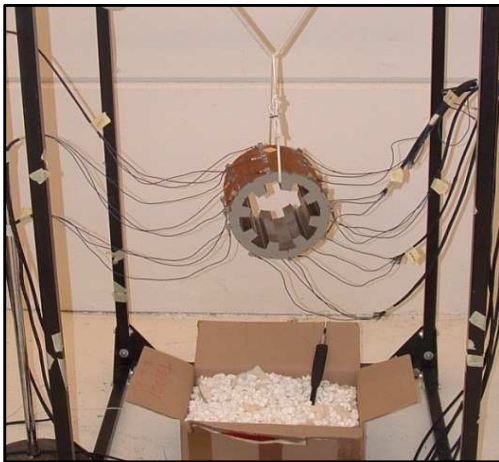


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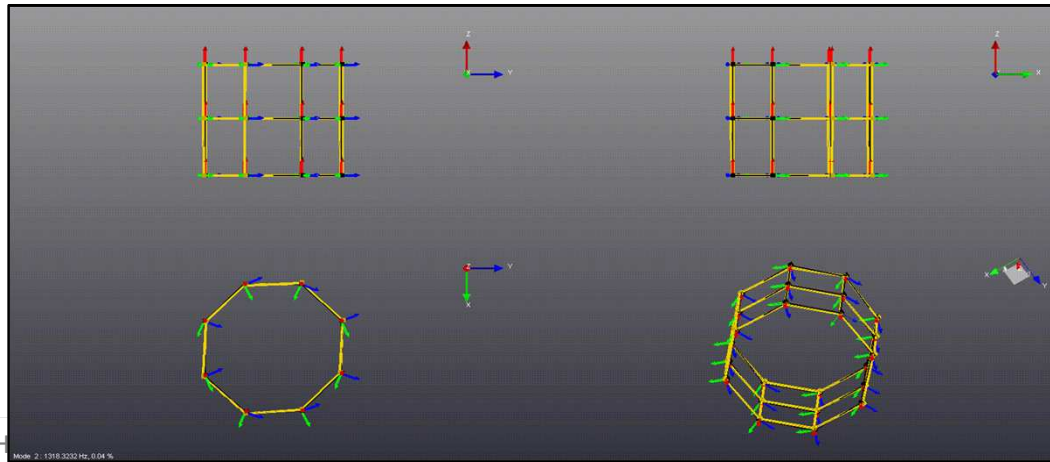
- Stator modelling
 - Stator FRFs testing
 - Stator Modal analysis
 - Stator modelling with anisotropic material properties
 - Correlation and updating to identify properties
- Highest focus on ovalisation modes
 - Good match with forcing pattern
 - Efficient radiator

Mode	TEST	CAE		Description
	Freq [Hz]	Freq [Hz] original	Freq [Hz] updated	
2,½	1255			
2,0a	1318	1293	1319	1 st ovalisation
2,0b	1342	1295	1343	1 st ovalisation (45 deg)
2,1	1632			
3,0	3527	3426	3526	3 rd ovalisation
4,0	5745	5541	5701	4 th ovalisation

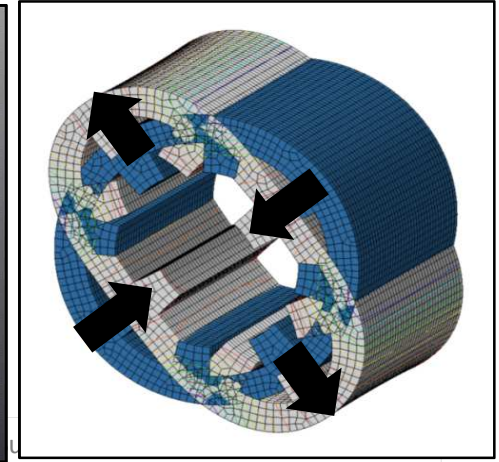
Stator FRF test



Stator TEST modes



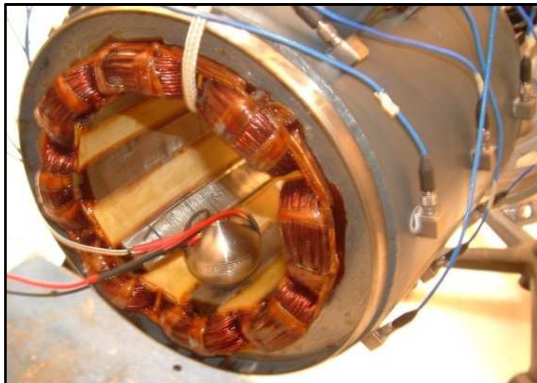
Stator CAE modes



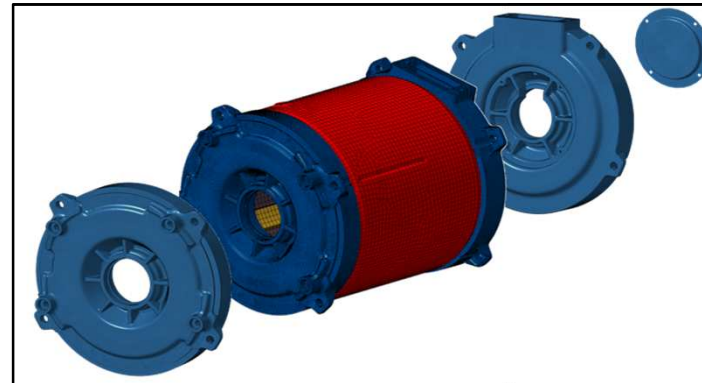
- Completion to full assembly
 - Windings
 - Housing (cooling jacket)
 - Effect of cooling water
 - End caps (covers)
- Step by step correlation with measurement data

<i>Mode</i>	<i>TEST</i>	<i>CAE</i>	<i>Description</i>
	<i>Freq [Hz]</i>	<i>Freq [Hz]</i>	
2,0a	1414	1400	1 st ovalisation
2,0b	1434	1412	1 st ovalisation (45 deg)

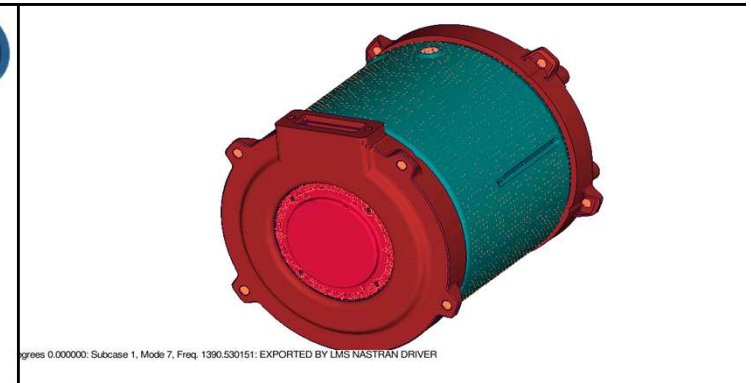
Assembly FRF test



Assembly Model



Assembly Mode



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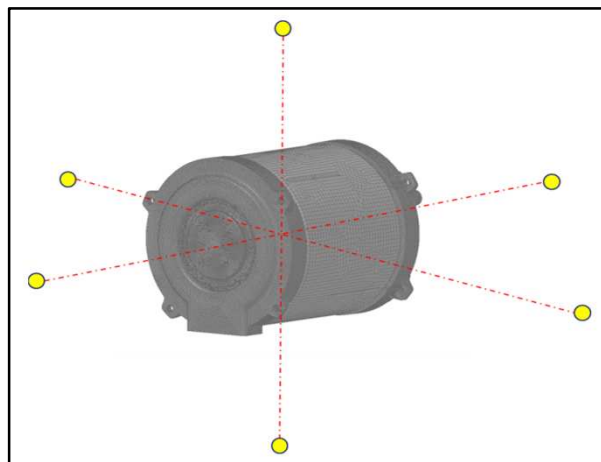
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- Structural Forced Response → surface vibrations for main motor orders (6,12,...)
- Creation of Acoustic model
 - Wrap of the structural model with free-field termination at boundary
 - 6 field microphones @ 1 m
- Calculation of pressure in field points resulting from surface vibrations

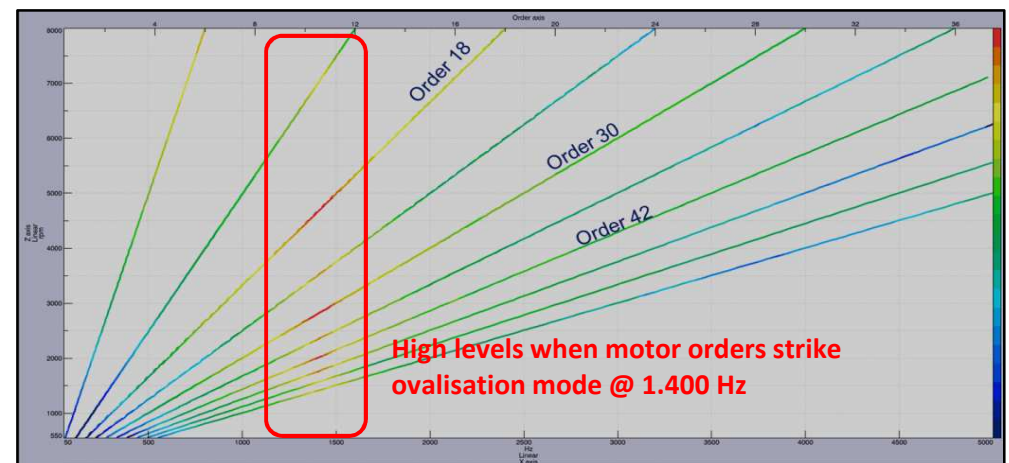
Acoustic model



Evaluation microphone positions



Noise at field point



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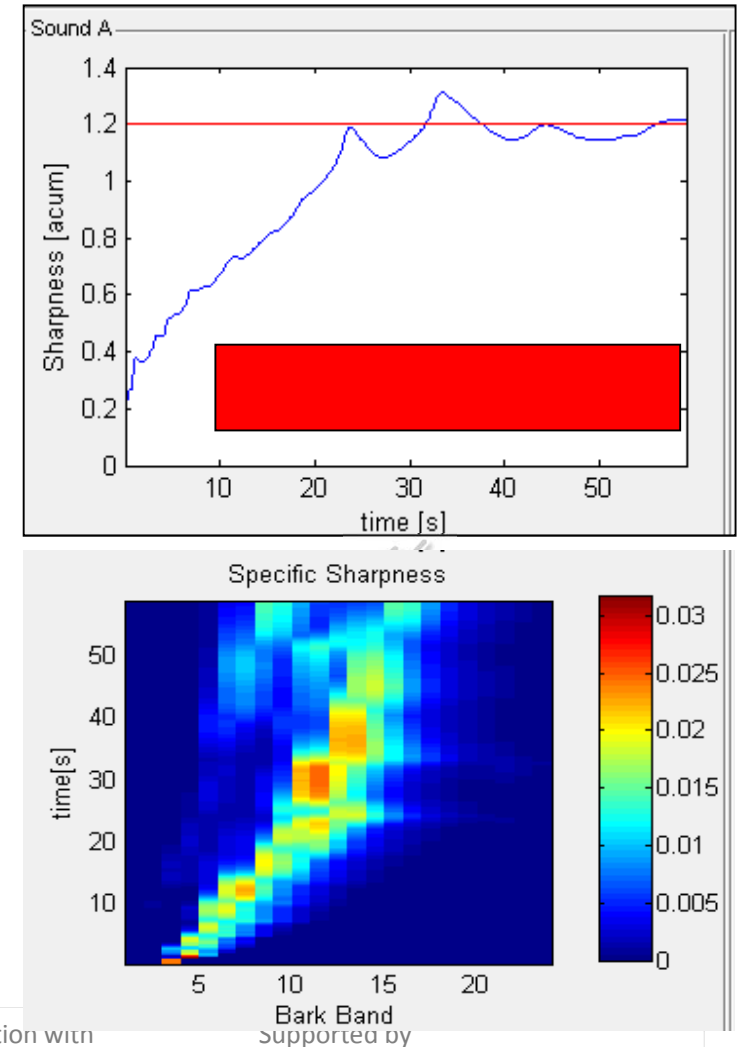
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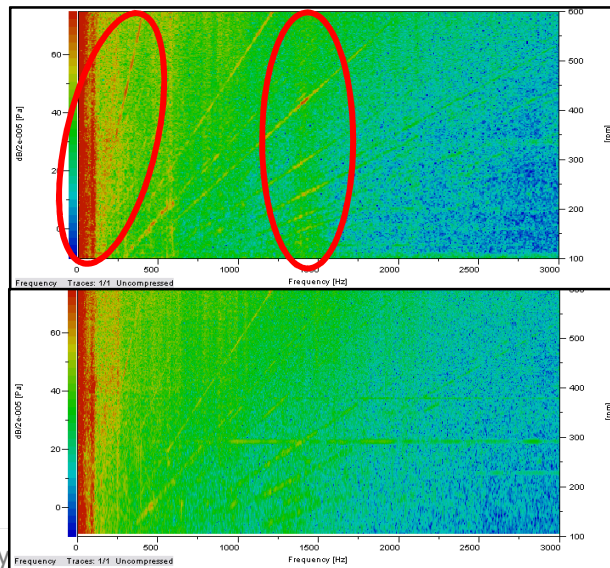
- Tonal noise is often perceived to be annoying, even when its sound level is not very high.
- Metrics related to level (OA level, dB(A), Loudness) are not appropriate for high frequency pure tone noise
- Dedicated metrics for tonal noise
 - Prominence ratio (*)
 - Tonality (*)
 - Sharpness

(*) Due to the lack of broad band noise data, not applicable for CAE results
- Sharpness is used to evaluate CAE results

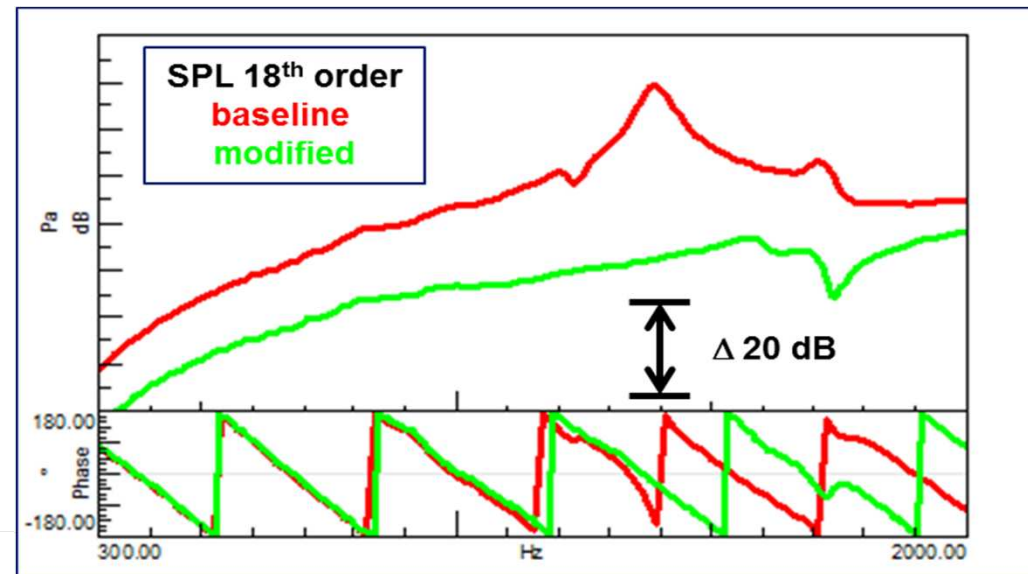


- Optimization of the motor control strategy allows to reduce the torque ripple, but can also be used to significantly reduce the noise radiated by the SRM
- Structural optimization of the motor and its housing allows to further reduce the noise radiated by the SR motor.
 - Simulation allows to understand the reasons behind high noise levels in certain rpm-ranges. Noise peaks typically occur when a motor order strikes a structural resonance and the stator force pattern matches well with the mode shape.
 - Design changes can be proposed, typically addressing resonance issues by adding damping to the structural modes.

Effect of Optimized Control Strategy



Effect of Structural Modifications



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- Switched Reluctance Motors are an interesting alternative to permanent magnet synchronous motors, but controlling their NVH behavior is a prerequisite to achieve a competitive solution.
- The noise radiation of electric motors can be optimized based on:
 - Electro-magnetic finite element models to obtain stator forces starting from current profiles
 - Vibro-acoustic finite element models to obtain housing vibrations & noise radiation based on stator forces
In view of their complex construction (laminates, ...), test based validation of the structural models is required
- The process can equally be applied to different motor types (e.g. permanent magnet synchronous motors).

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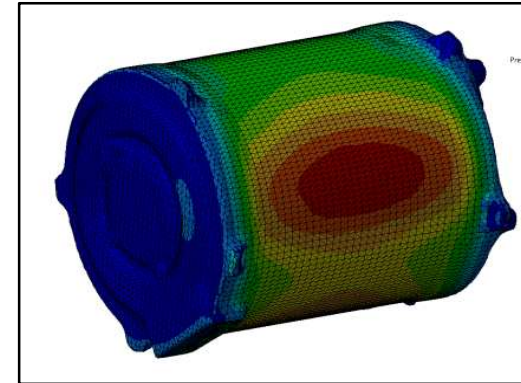
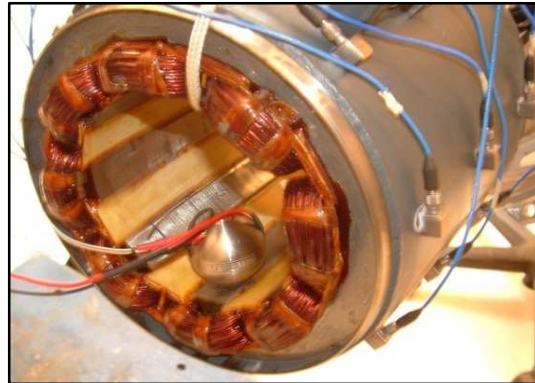
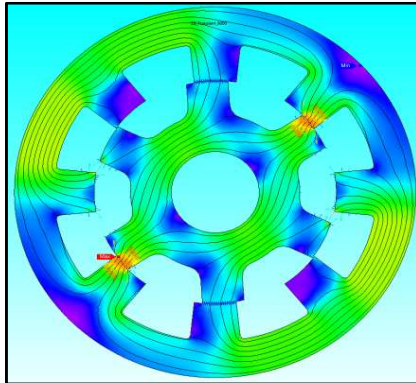
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Thank You!

...
Questions?



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