



The 27th INTERNATIONAL  
ELECTRIC VEHICLE  
SYMPOSIUM & EXHIBITION.

Barcelona, Spain  
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# Enhanced battery model including temperature effects

*Bogdan Roşca, TNO, Steven Wilkins, TNO*

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## Outline

1. Introduction TNO
2. Goal
3. Motivation of work
4. Battery modelling
5. Results
6. Applications
7. Conclusions

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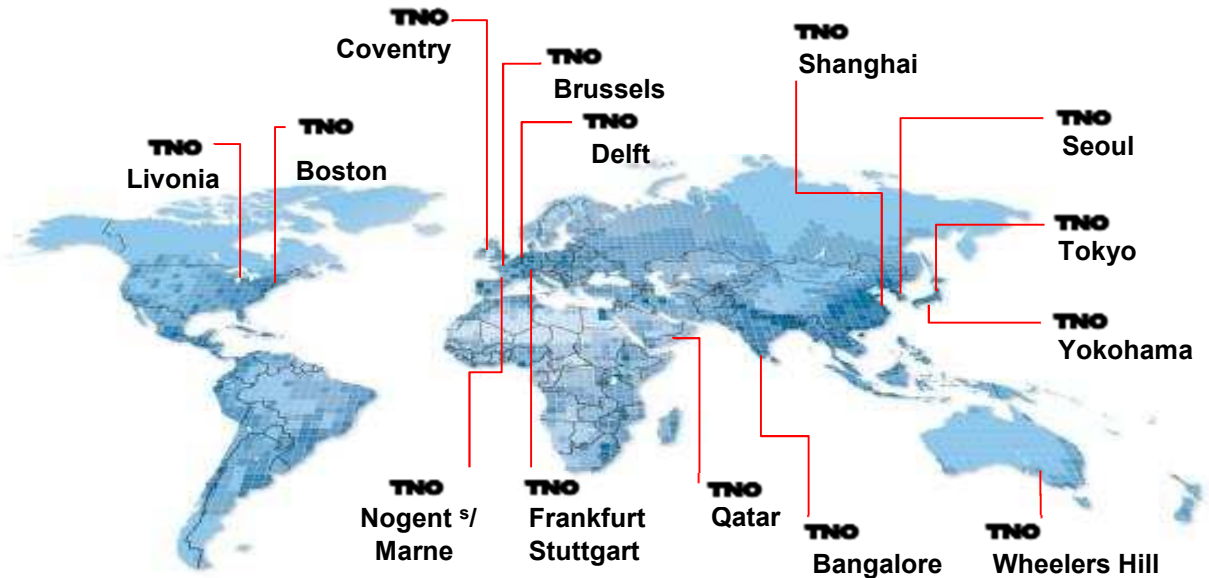
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## Introduction TNO

- TNO is the Netherlands' Organization for Applied Research
- Independent R&D organization
- Spin-off companies (e.g. )
- Over 75 years of experience
- 4,000 employees world-wide
- HQ in Delft, the Netherlands
- Annual turnover approx. 550 M€



### TNO Powertrains – R & D

- Detailed Powertrain Modelling and Control
- Energy and Emission Management
- Battery modelling and state estimation



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## Goal

*Develop a battery model which captures temperature influences on the battery electrical behaviour*

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## Motivation of work - performance

Battery performance strongly influenced by temperature

Accurate battery models needed for numerous automotive applications:

- Battery State-of-Charge (SoC) Estimation
- Battery Management Systems
- Range Prediction Algorithms
- Supervisory Control Algorithms

Higher accuracy over various operating temperatures → Temperature effects must be accounted for in battery modelling

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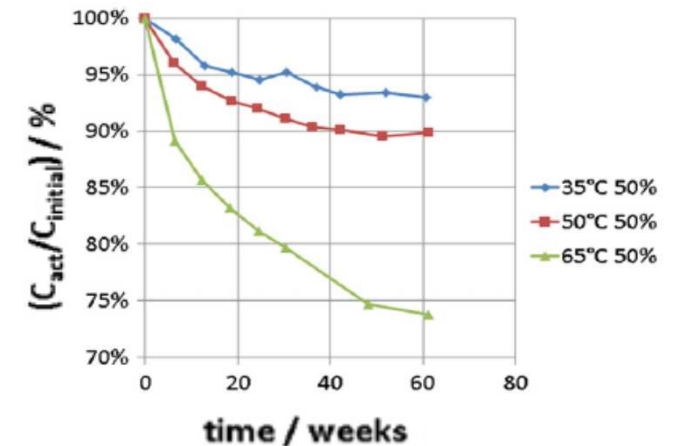
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## Motivation of work - ageing

Battery ageing influenced by temperature.

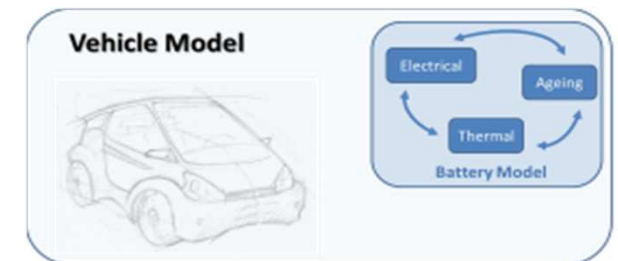


**ABattReLife European project:** battery ageing during vehicle usage and second life applications.



Vehicle simulator including coupled electro-thermal-ageing battery model used for sensitivity analysis of battery degradation phenomena in vehicular applications.

M. Ecker et al - Development of a lifetime prediction model for lithium-ion batteries based on extended accelerated ageing test data



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## TNO use cases

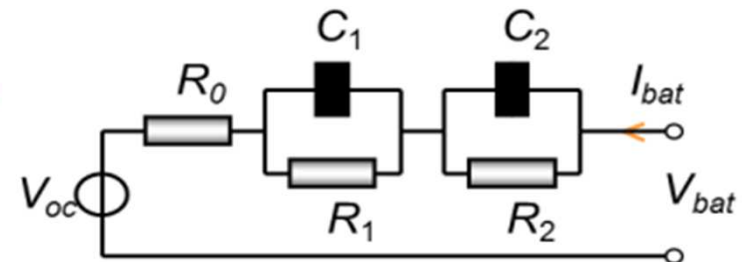
- SoC estimation, BMS, System level simulation, Total Cost of Ownership (TCO) tools

## Approach

- Electric circuit equivalent, phenomenological dynamic battery model
- On-line implementable
- Temperature dependent components
- Automatic model identification procedure starting from measurements

$$\begin{pmatrix} SoC_k \\ V_{1,k} \\ V_{2,k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 - \frac{\Delta t}{R_1 C_1} & 0 \\ 0 & 0 & 1 - \frac{\Delta t}{R_2 C_2} \end{pmatrix} \begin{pmatrix} SoC_{k-1} \\ V_{1,k-1} \\ V_{2,k-1} \end{pmatrix} + \begin{pmatrix} \frac{\Delta t}{C_1} \\ \frac{\Delta t}{C_1} \\ \frac{\Delta t}{C_2} \end{pmatrix} I_{bat,k-1}$$

$$V_{bat,k} = V_{oc}(SoC_k, T_k) + V_{1,k} + V_{2,k} + R_0(SoC_k, T_k)I_{bat,k}$$



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## TNO use cases

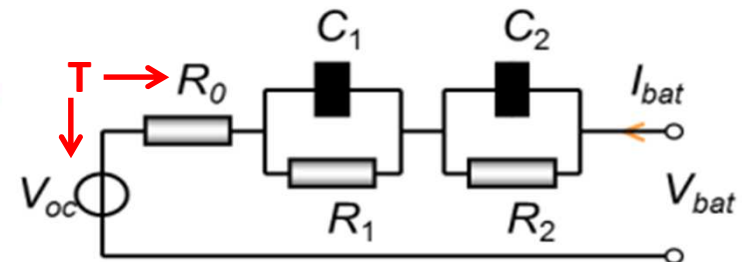
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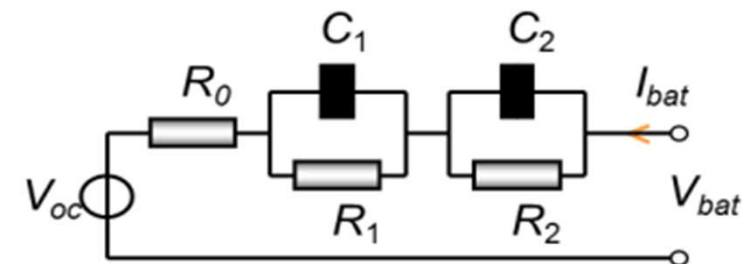
## Experimental validation

- Battery cycling within a climatic chamber

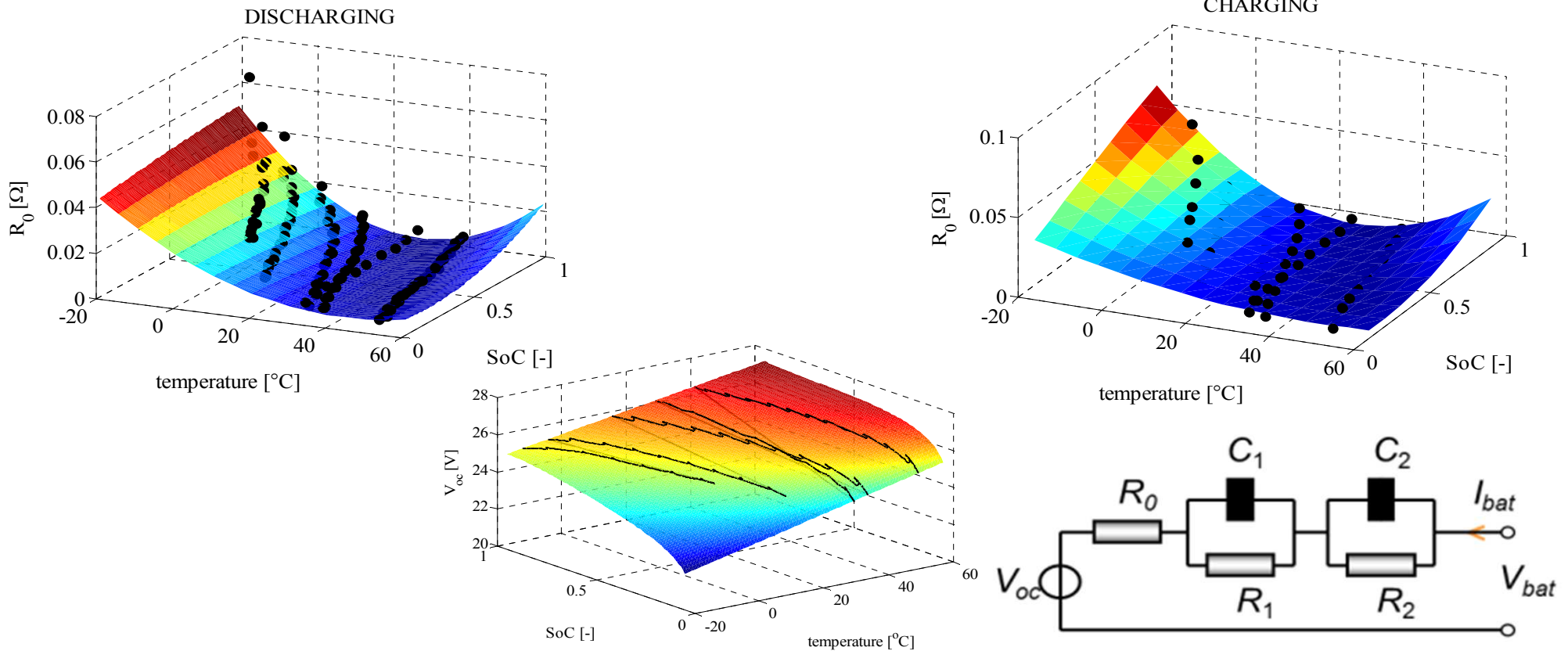
Test number	1	2	3	4	5	6
Ambient temperature [°C]	-18	-10	0	10	25	40

- Validation approach: tests 1, 2, 4, 5 and 6 used for **model identification** and test 3 for **model validation**

Test number	1	2	3	4	5	6
Ambient temperature [°C]	-18	-10	0	10	25	40



## Model identification



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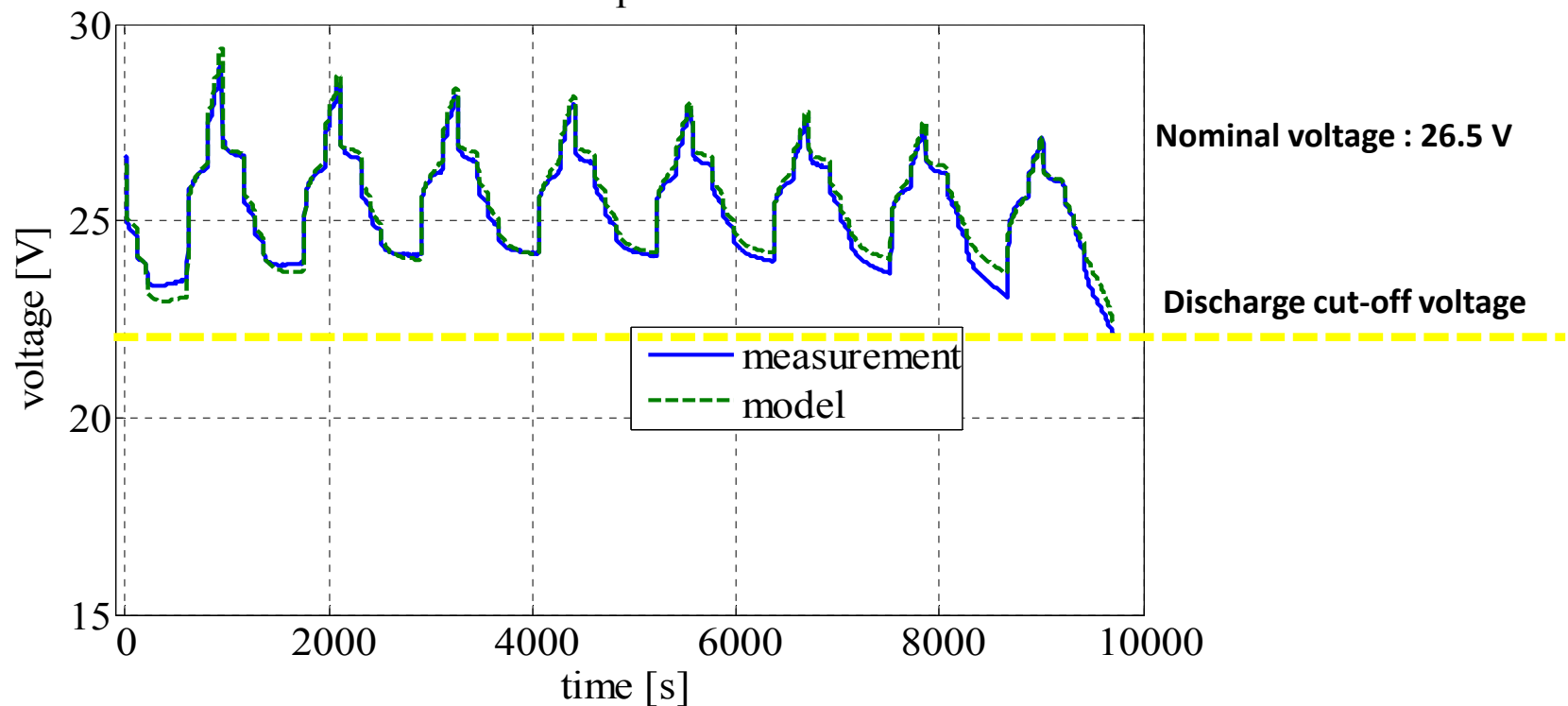
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## Experimental validation

Model validation - voltage prediction  
ambient temperature: 0°C



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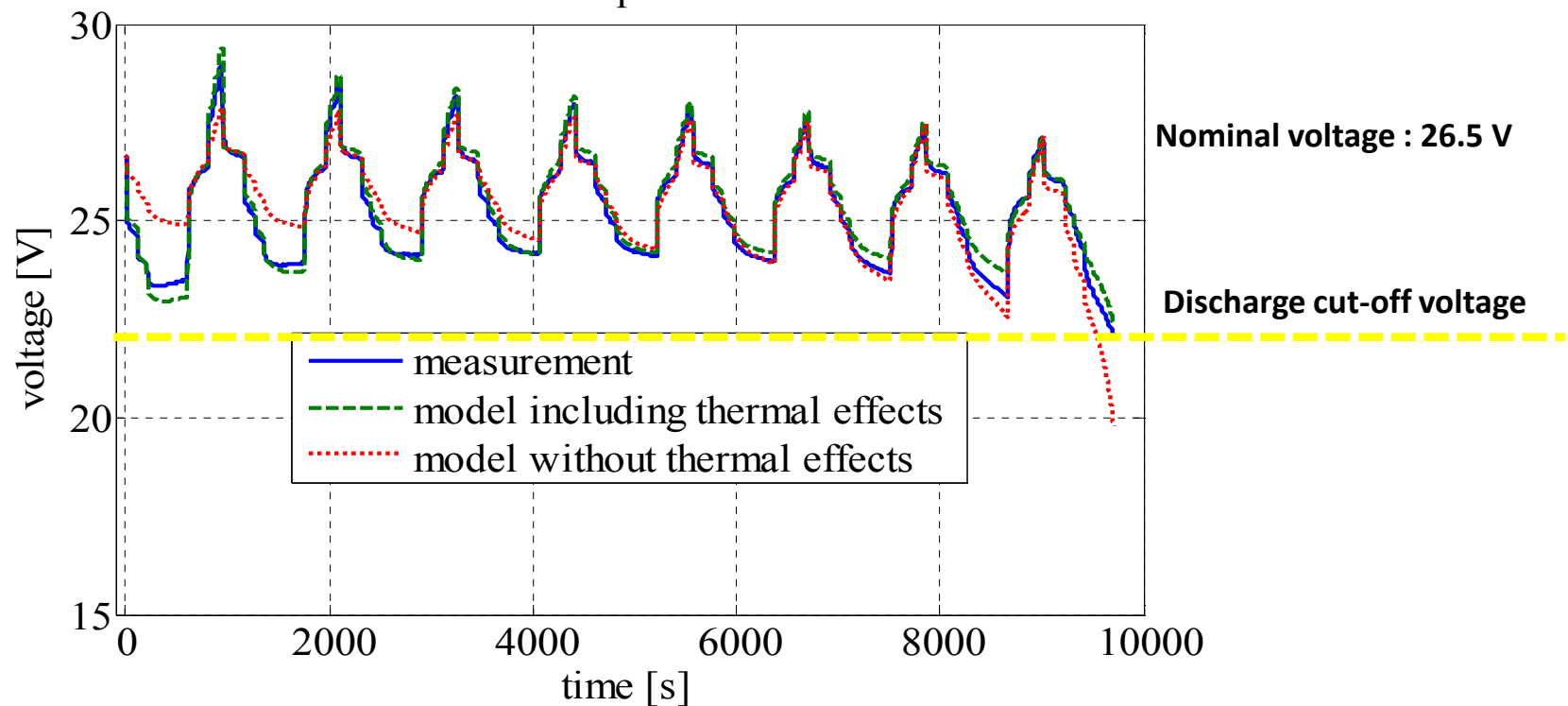
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## Experimental validation

Model validation - voltage prediction  
ambient temperature: 0°C



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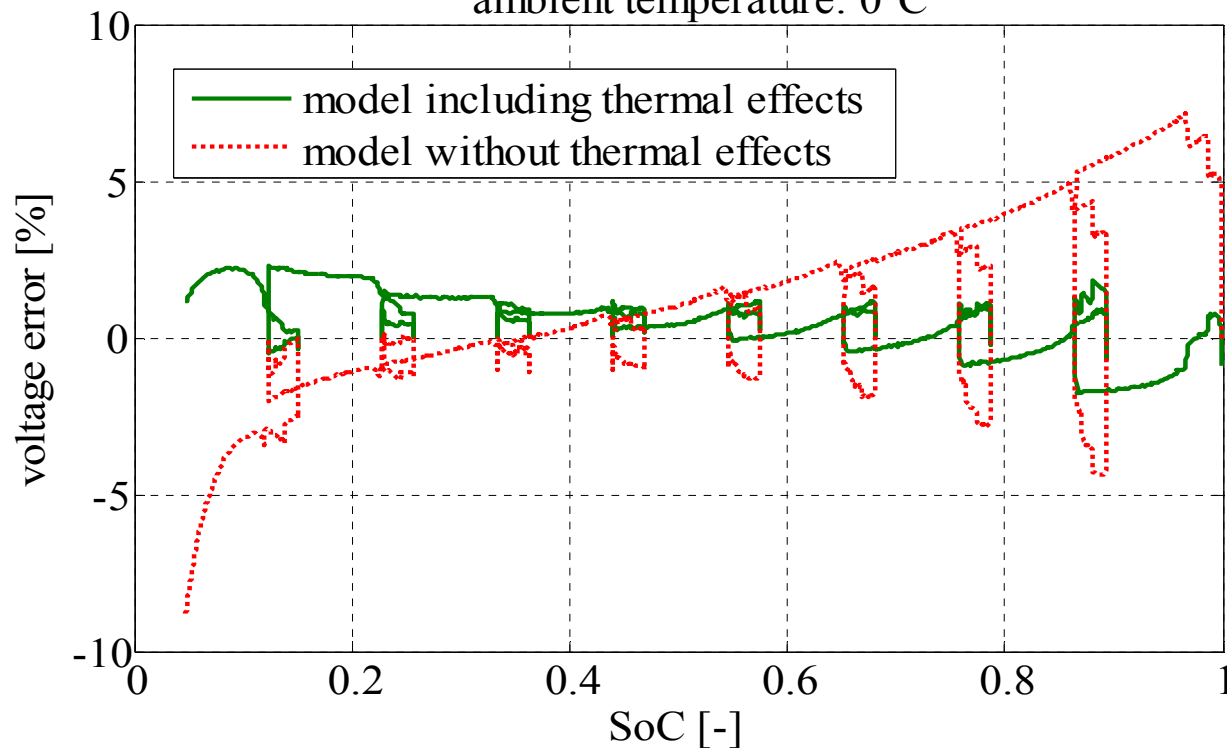
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## Experimental validation

Model validation - voltage prediction error  
ambient temperature: 0°C



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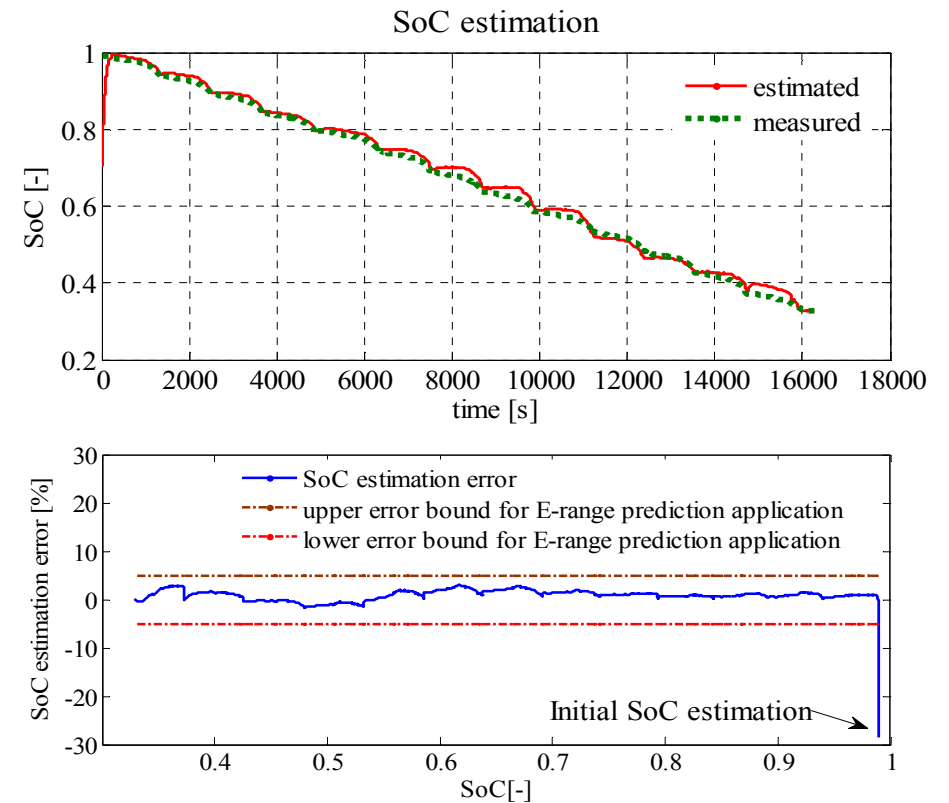
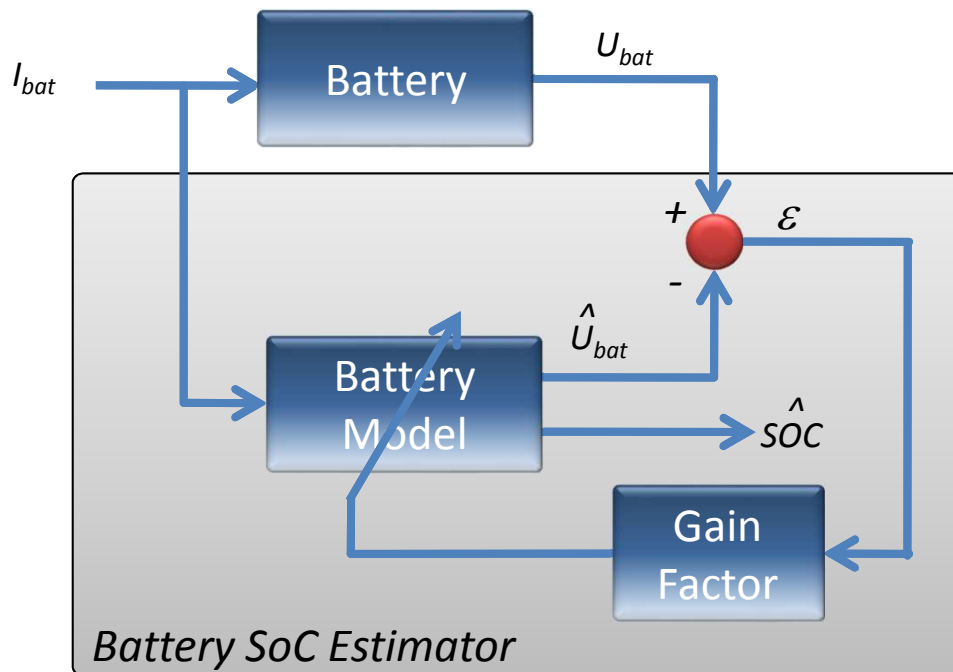


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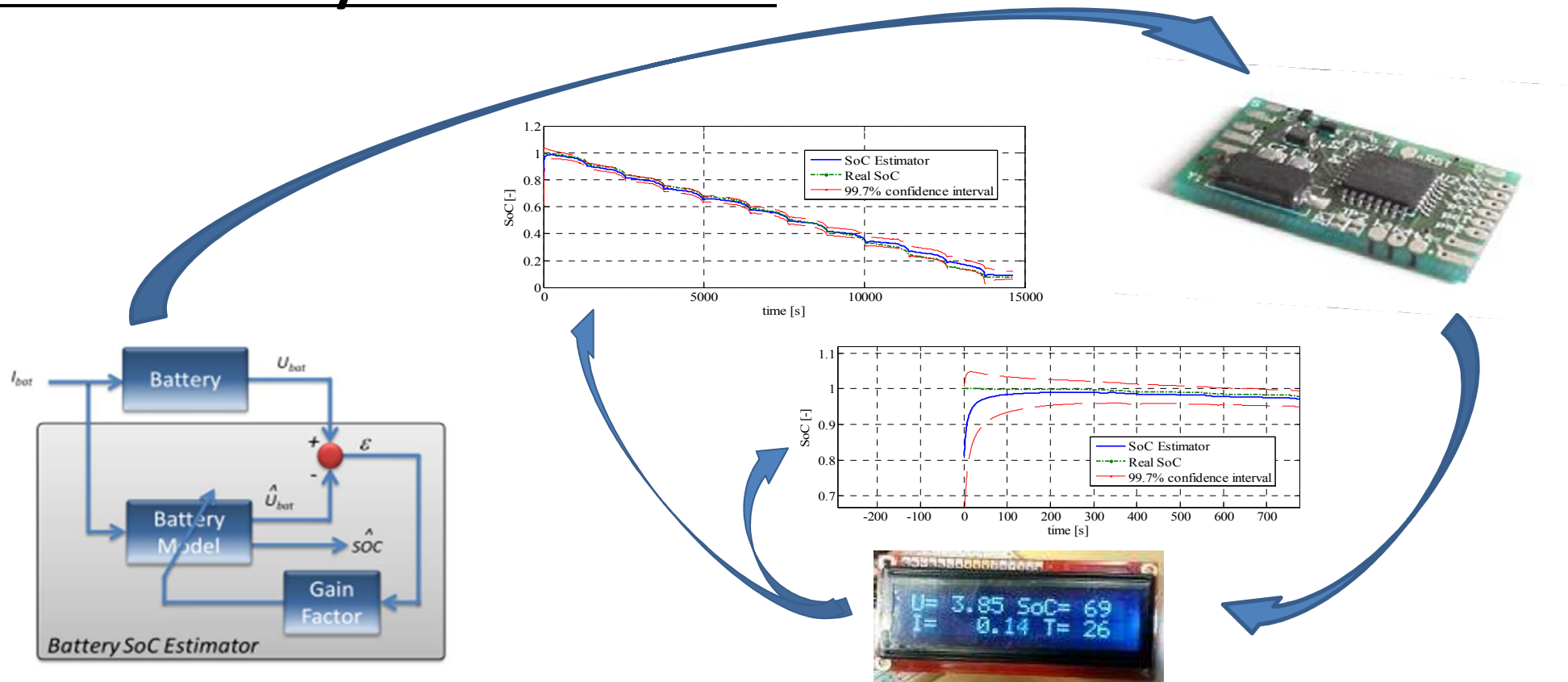


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## Battery state estimator - SoC



### Robust battery state estimation



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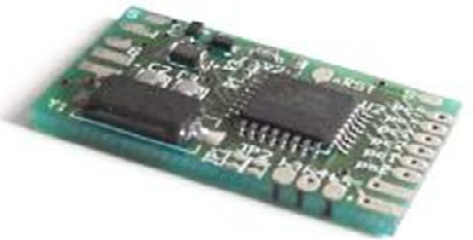
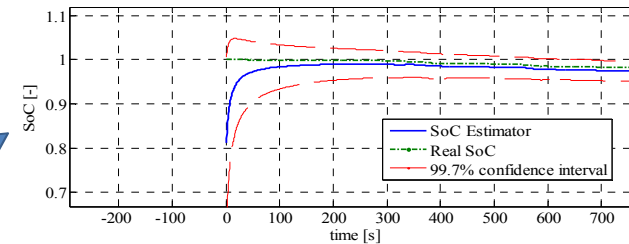
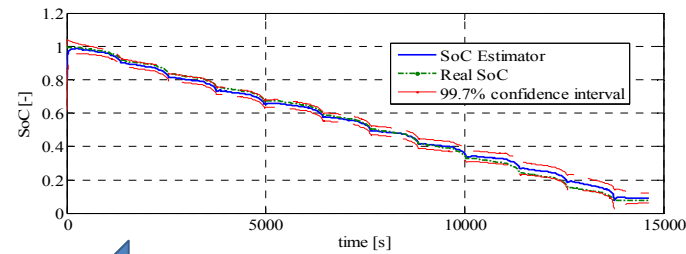
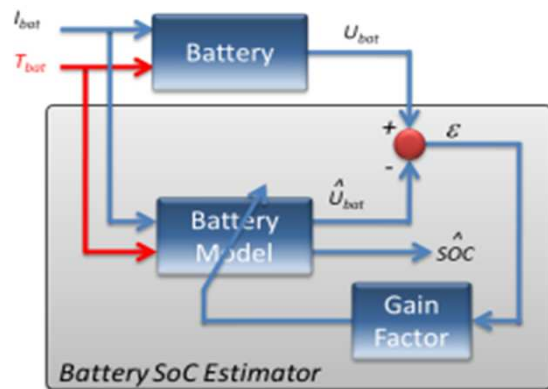
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### Robust battery state estimation



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## Conclusions

- **Temperature** has a **strong influence** on battery performance and ageing behavior
- To correctly capture that influence, temperature effects have been included in the existing battery model, leading to **increased model accuracy** under different operating temperatures
- Enhanced battery model supports the development of embedded **SoC estimation** algorithms
- Enhanced battery model supports the development of battery lifetime assessment tools, essential for **Total Cost of Ownership** analysis for hybrid and electric vehicles

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Thank you for your attention!

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Top down vs. bottom up modelling

Top down – simple, fast, many simplifying assumptions

Bottom up – more complex, more effort needed, different layers of validation, can capture subsystem interactions

Choice: application dependent

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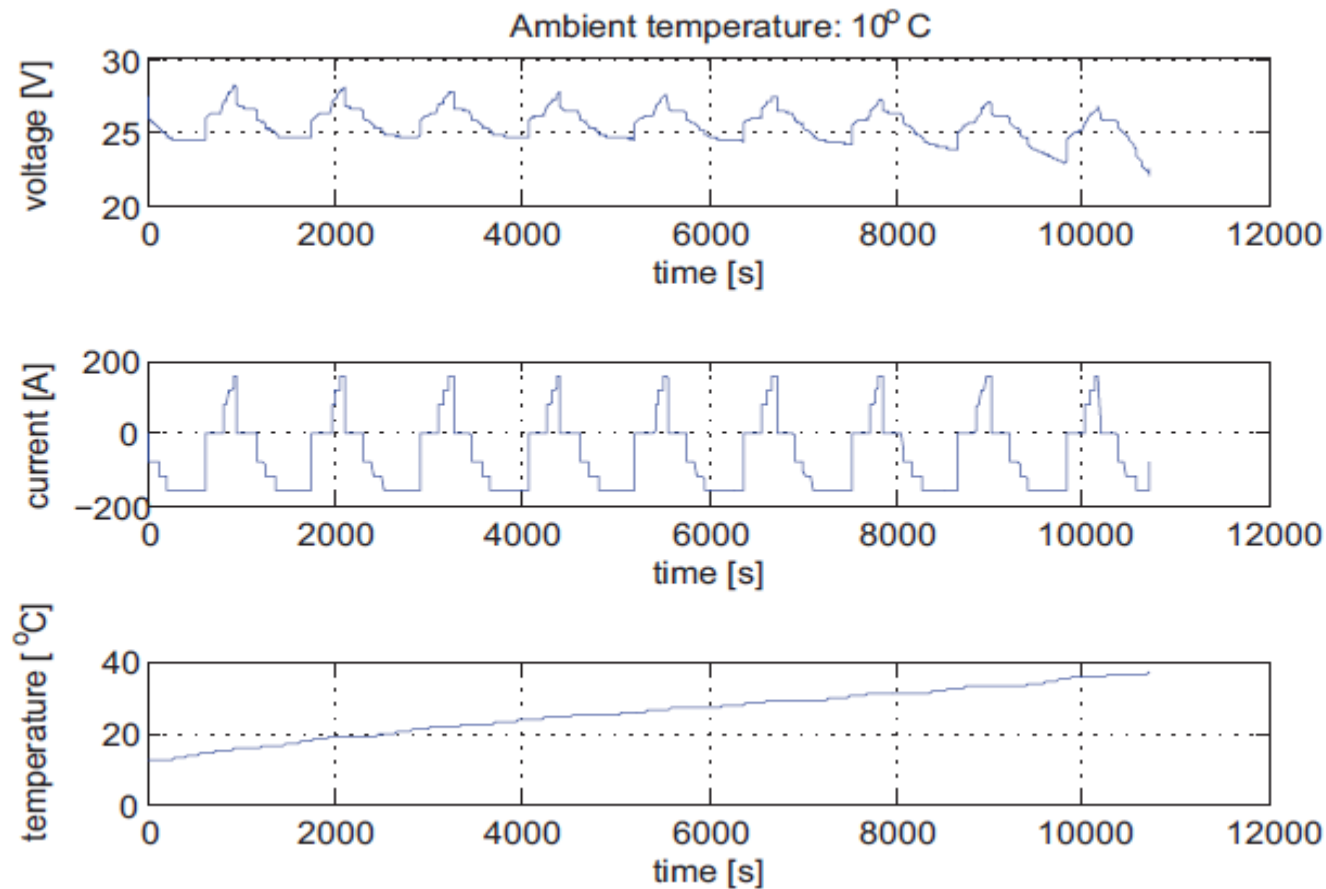


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