



The 27th INTERNATIONAL
ELECTRIC VEHICLE
SYMPOSIUM & EXHIBITION.

Barcelona, Spain
17th-20th November 2013

Enhanced battery model including temperature effects

Bogdan Roșca, TNO, Steven Wilkins, TNO

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Outline

1. Introduction TNO
2. Goal
3. Motivation of work
4. Battery modelling
5. Results
6. Applications
7. Conclusions

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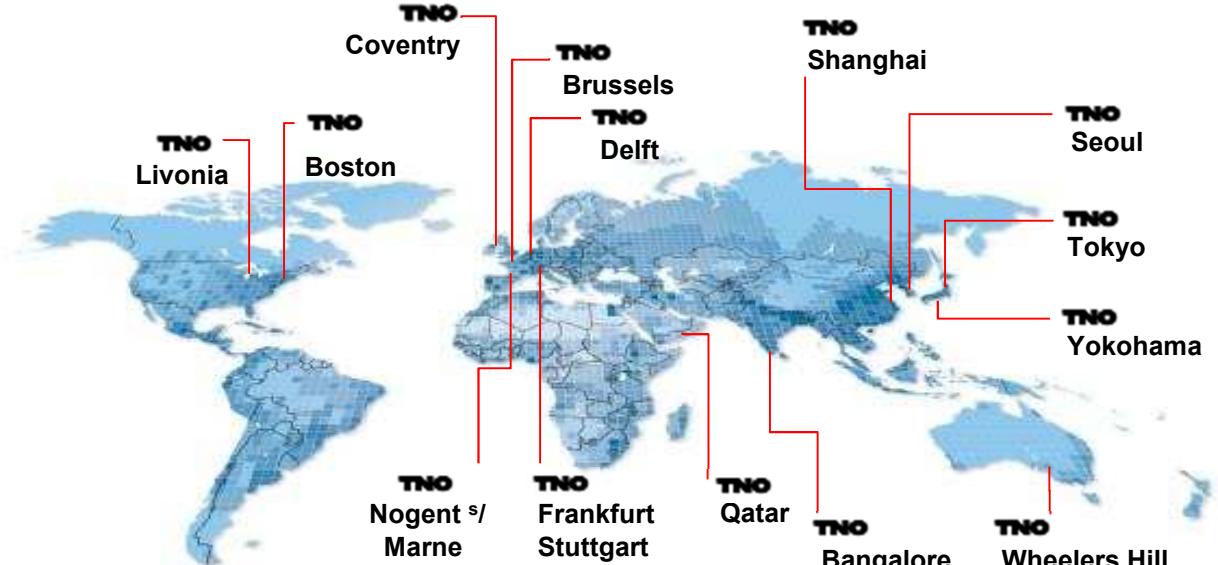


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Introduction TNO

- TNO is the Netherlands' Organization for Applied Research
- Independent R&D organization
- Spin-off companies (e.g. 
- Over 75 years of experience
- 4,000 employees world-wide
- HQ in Delft, the Netherlands
- Annual turnover approx. 550 M€



TNO Powertrains – R & D

- Detailed Powertrain Modelling and Control
- Energy and Emission Management
- Battery modelling and state estimation



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Goal

Develop a battery model which captures temperature influences on the battery electrical behaviour

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Motivation of work - performance

Battery performance strongly influenced by temperature

Accurate battery models needed for numerous automotive applications:

- Battery State-of-Charge (SoC) Estimation
- Battery Management Systems
- Range Prediction Algorithms
- Supervisory Control Algorithms

Higher accuracy over various operating temperatures → Temperature effects must be accounted for in battery modelling

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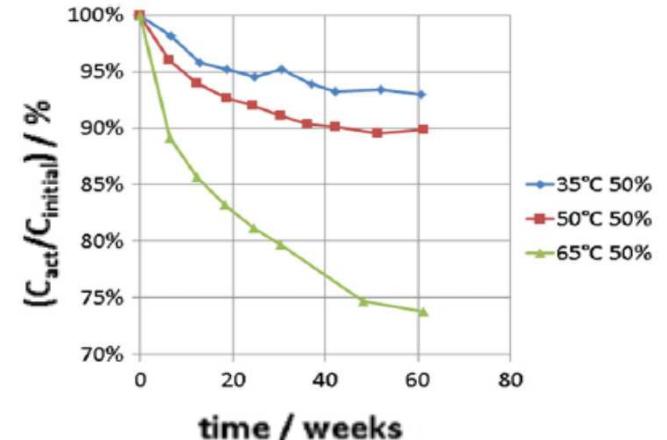
Motivation of work - ageing

Battery ageing influenced by temperature.

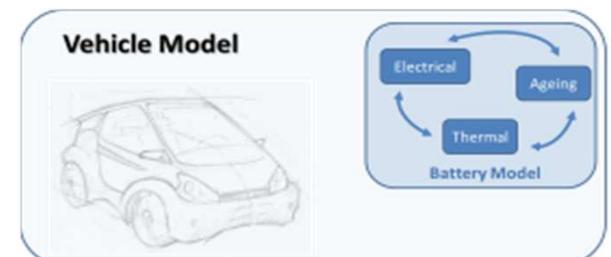
ABattReLife European project: battery ageing during vehicle usage and second life applications.



Vehicle simulator including coupled electro-thermal-ageing battery model used for sensitivity analysis of battery degradation phenomena in vehicular applications.



M. Ecker et al - *Development of a lifetime prediction model for lithium-ion batteries based on extended accelerated aging test data*



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TNO use cases

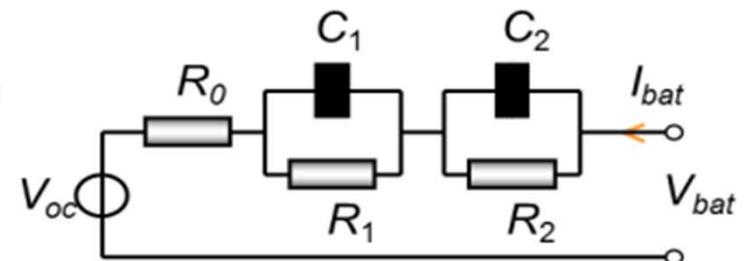
- SoC estimation, BMS, System level simulation, Total Cost of Ownership (TCO) tools

Approach

- Electric circuit equivalent, phenomenological dynamic battery model
- On-line implementable
- Temperature dependent components
- Automatic model identification procedure starting from measurements

$$\begin{pmatrix} SoC_k \\ V_{1,k} \\ V_{2,k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 - \frac{\Delta t}{R_1 C_1} & 0 \\ 0 & 0 & 1 - \frac{\Delta t}{R_2 C_2} \end{pmatrix} \begin{pmatrix} SoC_{k-1} \\ V_{1,k-1} \\ V_{2,k-1} \end{pmatrix} + \begin{pmatrix} \frac{\Delta t}{C_1} \\ \frac{\Delta t}{C_1} \\ \frac{\Delta t}{C_2} \end{pmatrix} I_{bat,k-1}$$

$$V_{bat,k} = V_{oc}(SoC_k, T_k) + V_{1,k} + V_{2,k} + R_0(SoC_k, T_k) I_{bat,k}$$



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TNO use cases

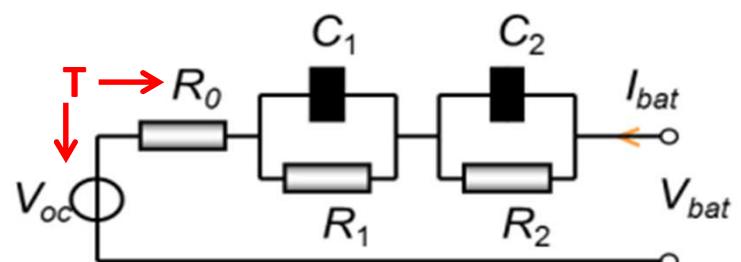
- SoC estimation, BMS, System level simulation, Total Cost of Ownership (TCO) tools

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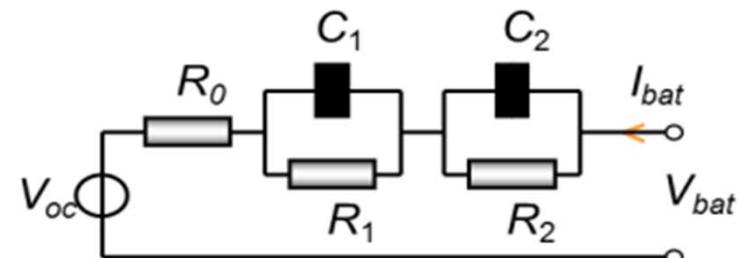
Experimental validation

- Battery cycling within a climatic chamber

Test number	1	2	3	4	5	6
Ambient temperature [°C]	-18	-10	0	10	25	40

- Validation approach: tests 1, 2, 4, 5 and 6 used for **model identification** and test 3 for **model validation**

Test number	1	2	3	4	5	6
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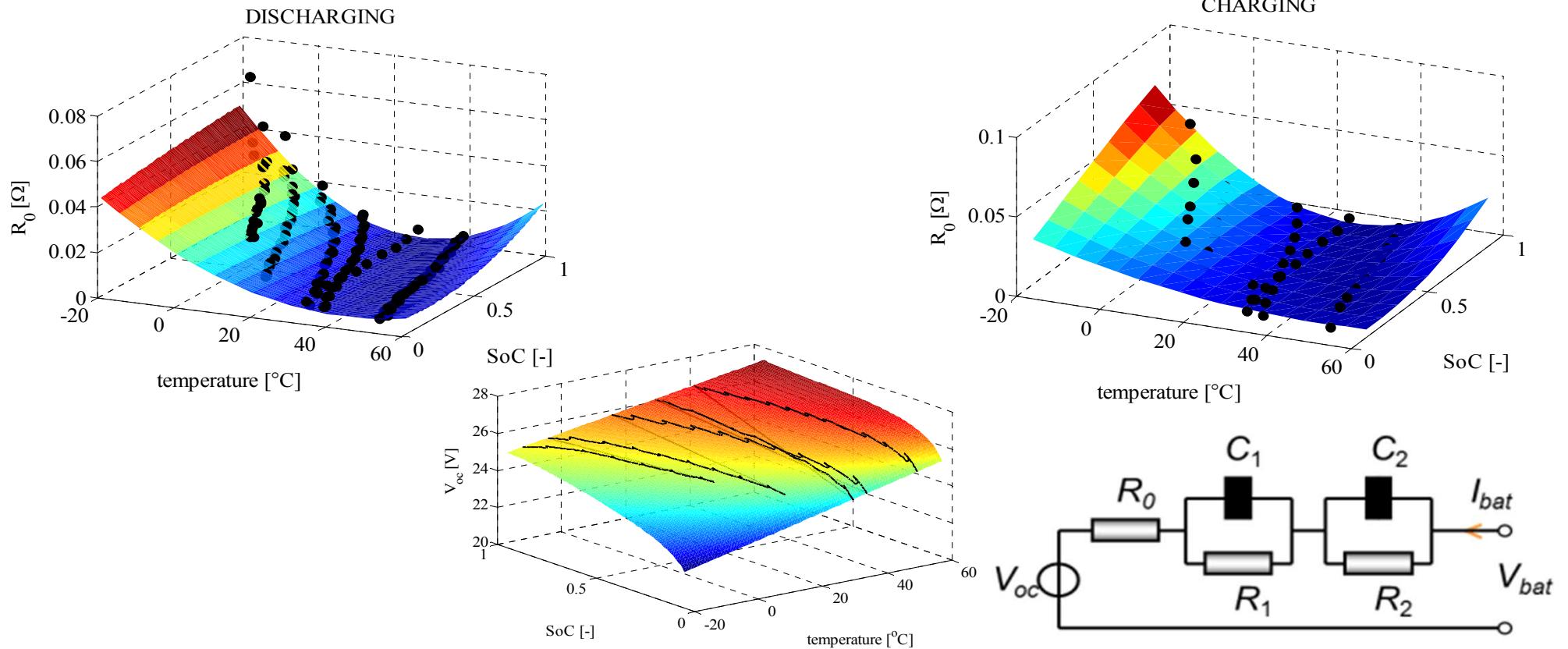
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Model identification



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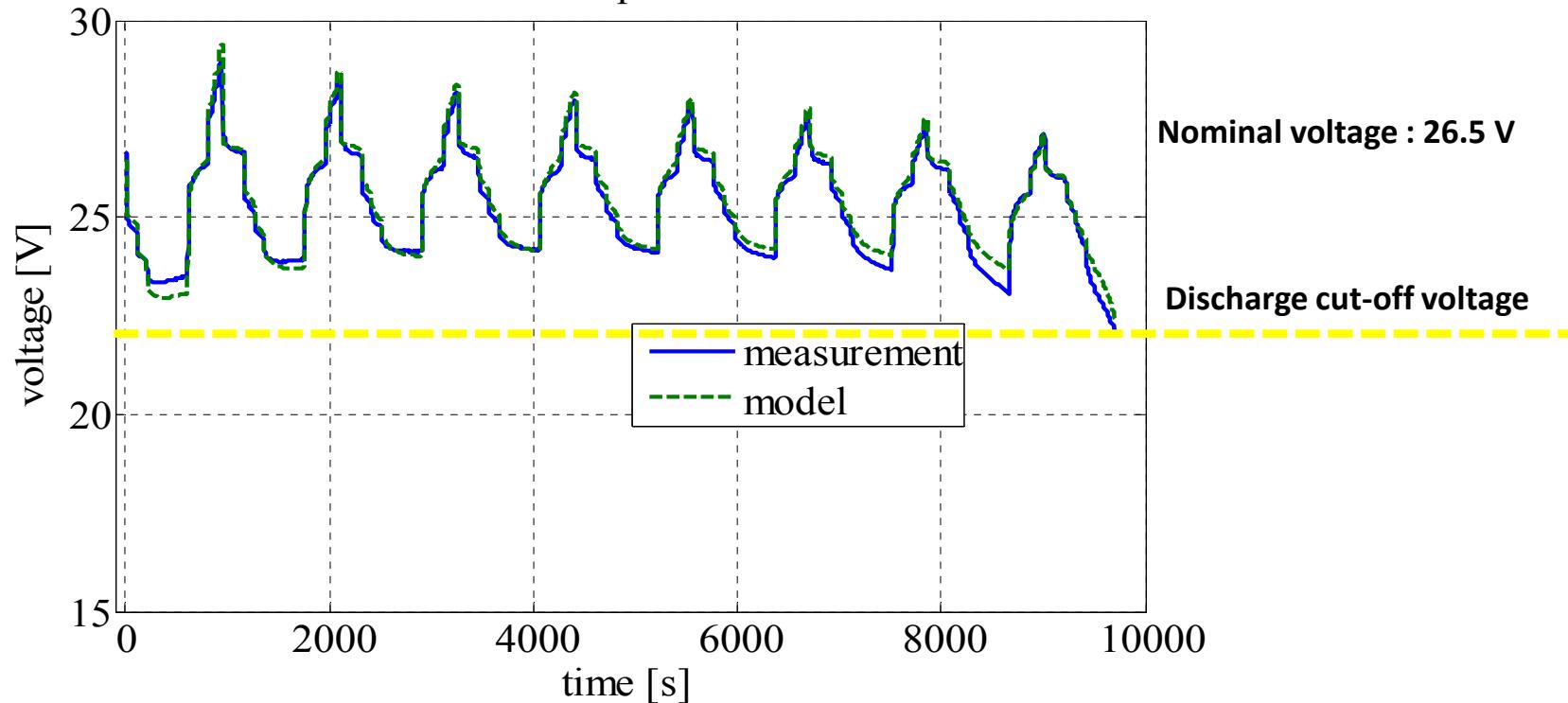


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Experimental validation

Model validation - voltage prediction
ambient temperature: 0°C



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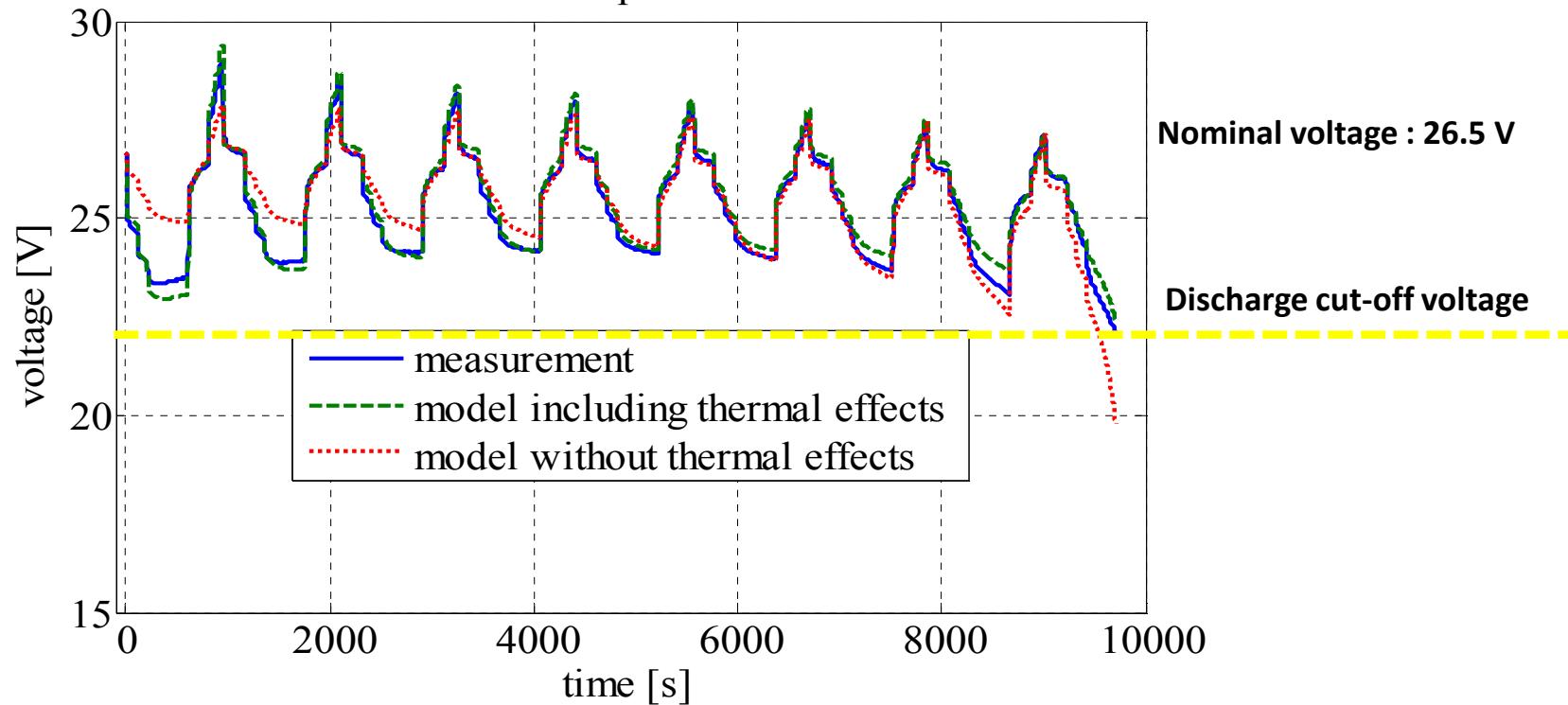
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Experimental validation

Model validation - voltage prediction
ambient temperature: 0°C



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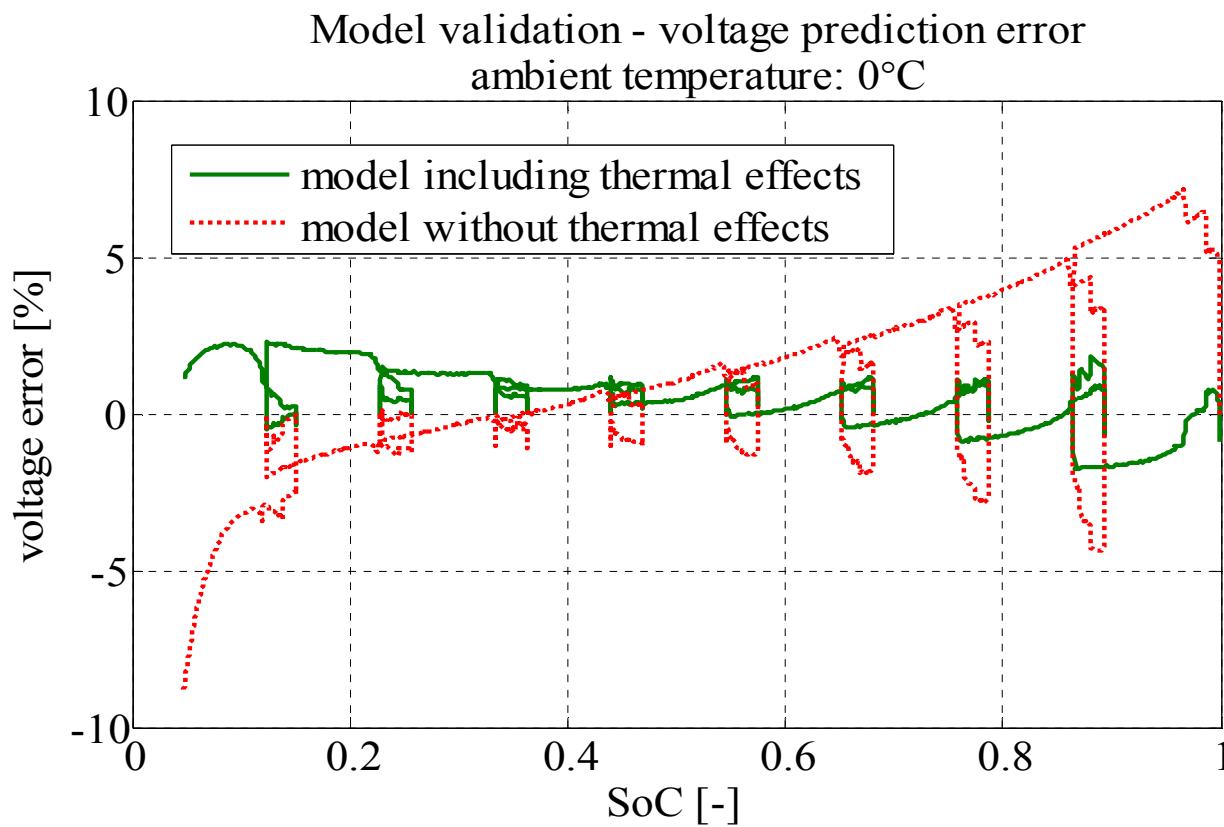


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Experimental validation



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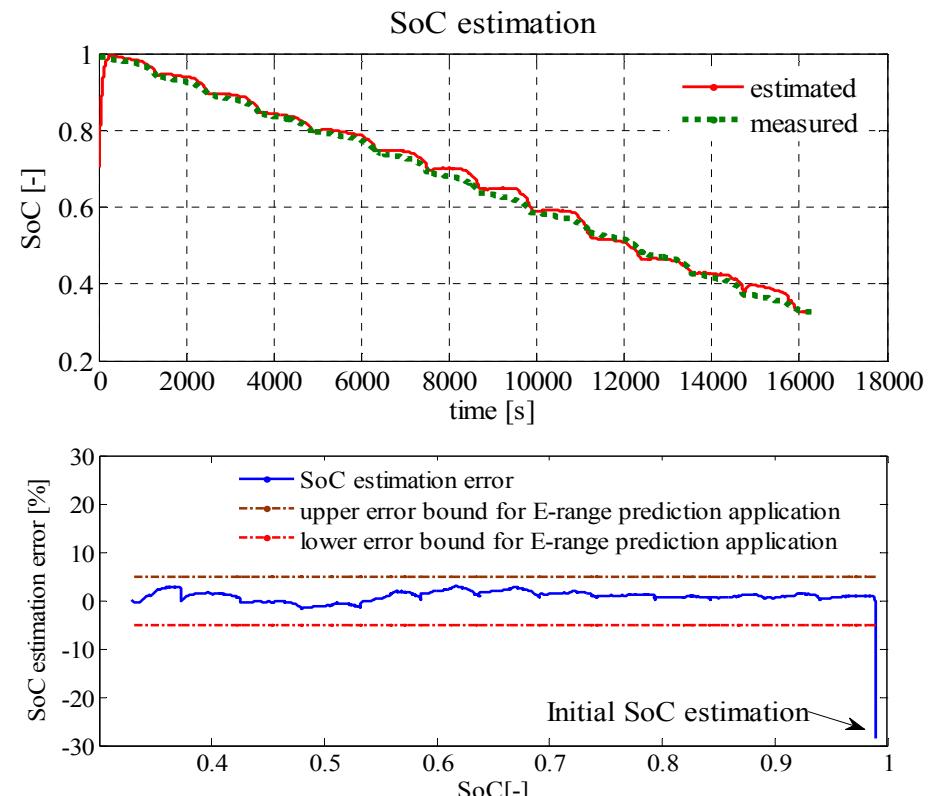
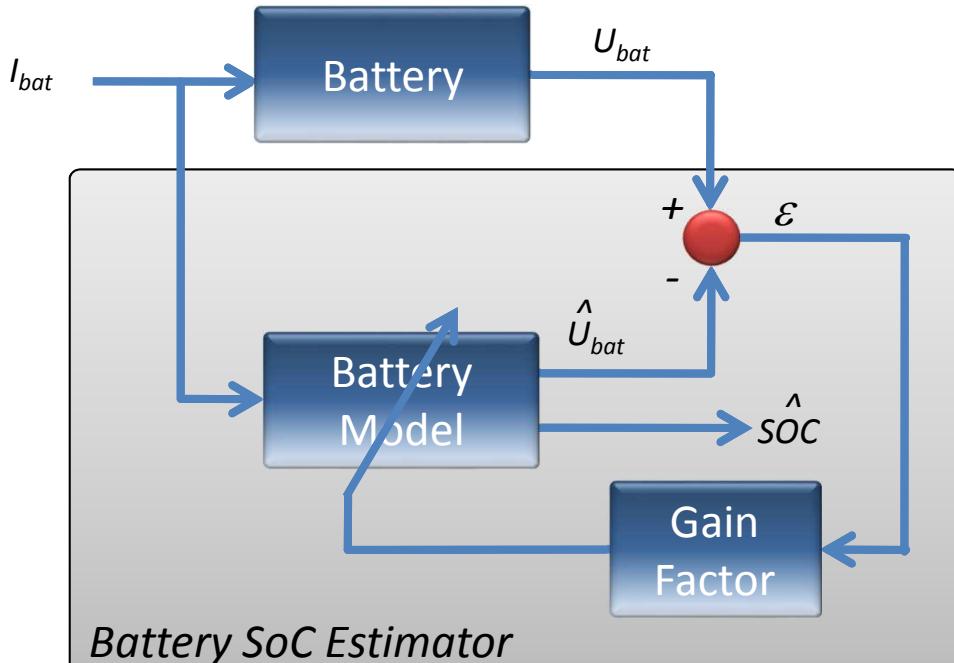
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Battery state estimator - SoC



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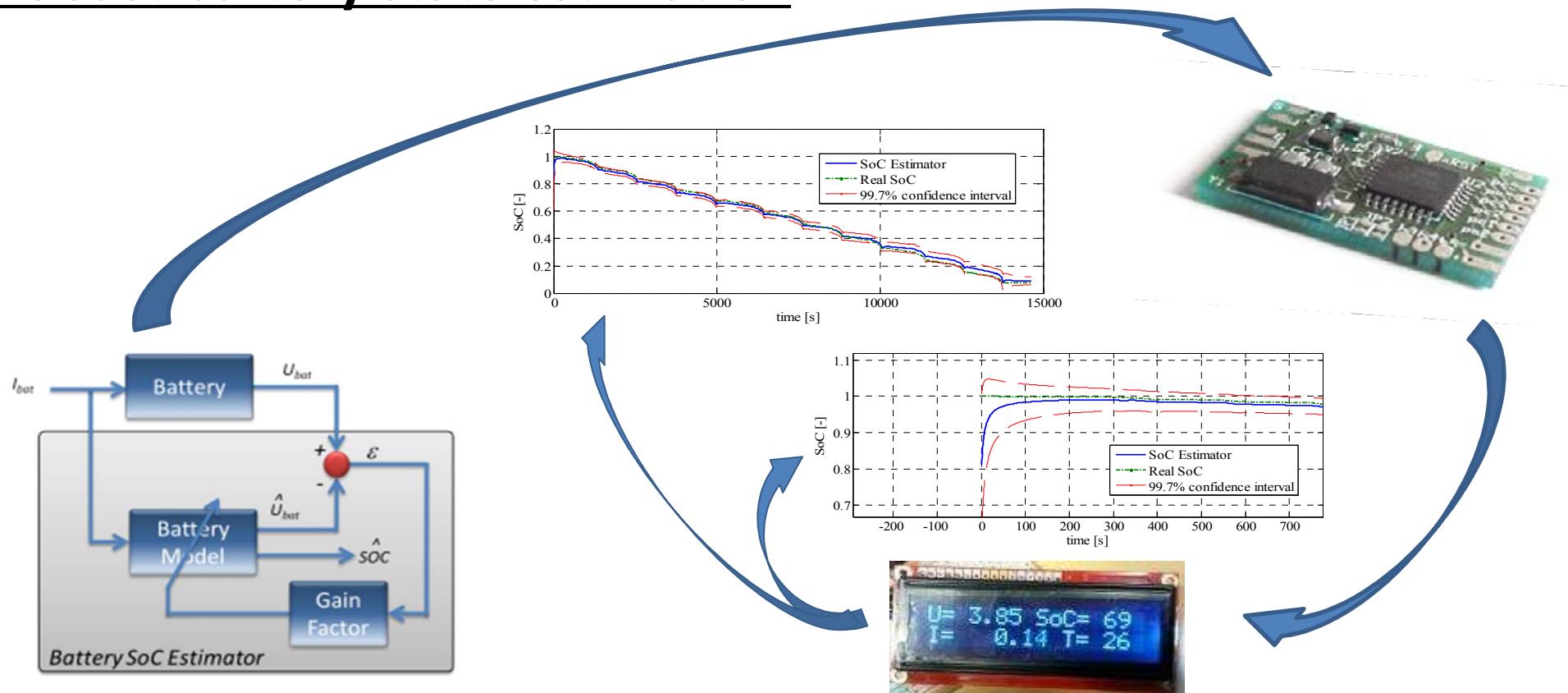
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Robust battery state estimation



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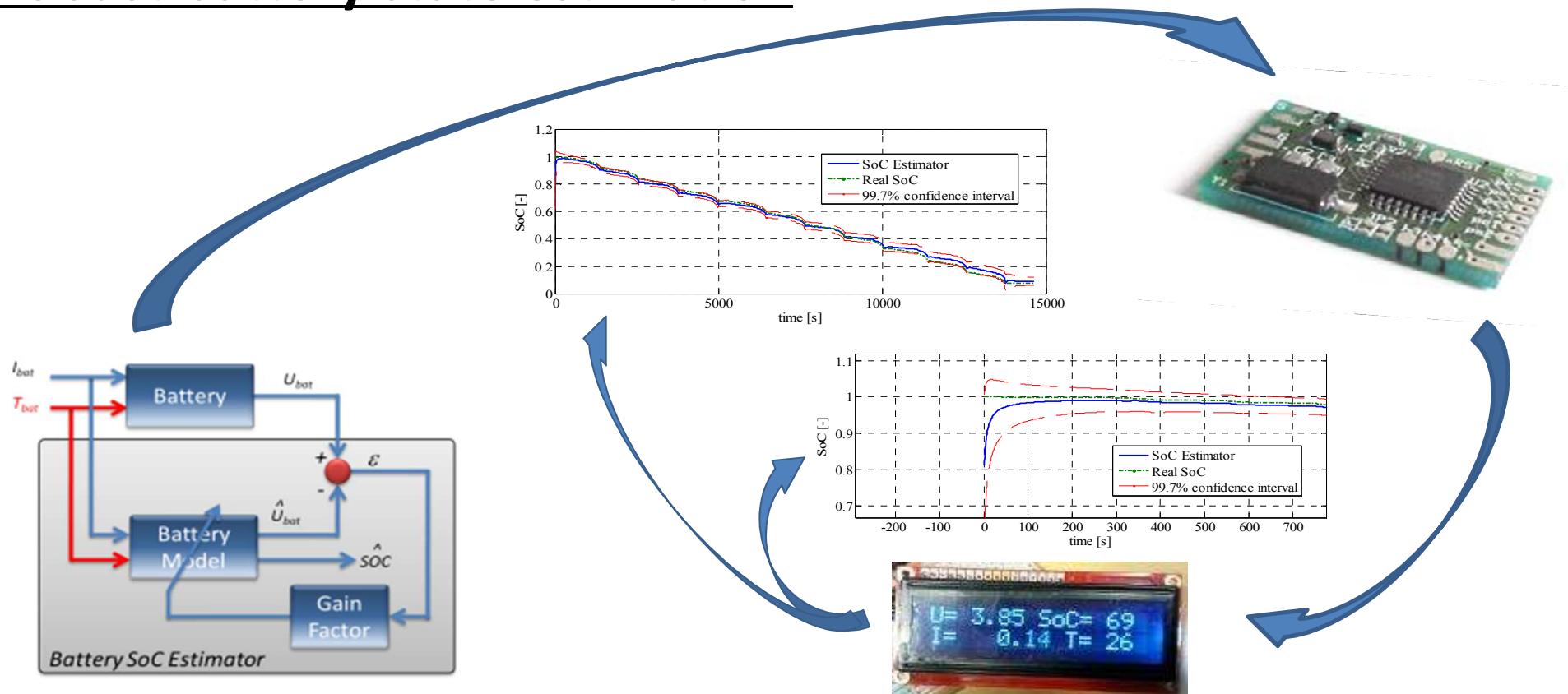
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Robust battery state estimation



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Conclusions

- **Temperature has a strong influence** on battery performance and ageing behavior
- To correctly capture that influence, temperature effects have been included in the existing battery model, leading to **increased model accuracy** under different operating temperatures
- Enhanced battery model supports the development of embedded **SoC estimation** algorithms
- Enhanced battery model supports the development of battery lifetime assessment tools, essential for **Total Cost of Ownership** analysis for hybrid and electric vehicles

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Thank you for your attention!

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Top down vs. bottom up modelling

Top down – simple, fast, many simplifying assumptions

Bottom up – more complex, more effort needed, different layers of validation, can capture subsystem interactions

Choice: application dependent

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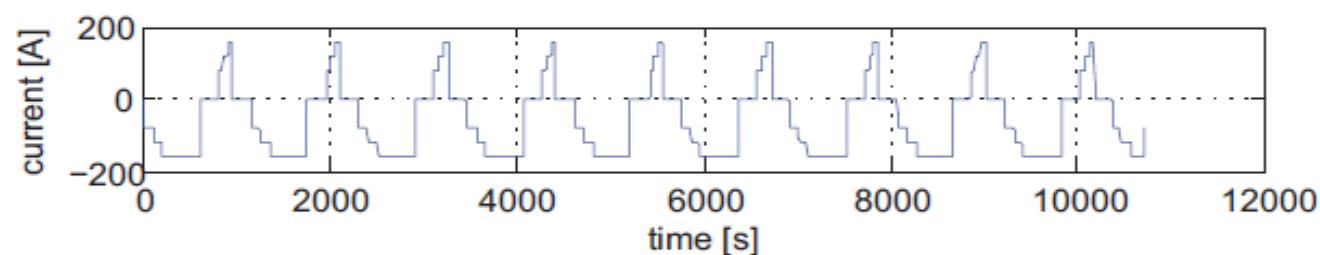
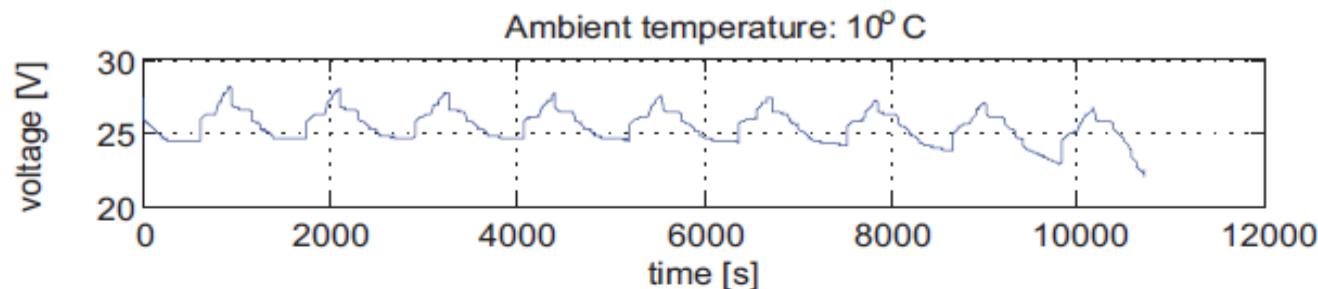


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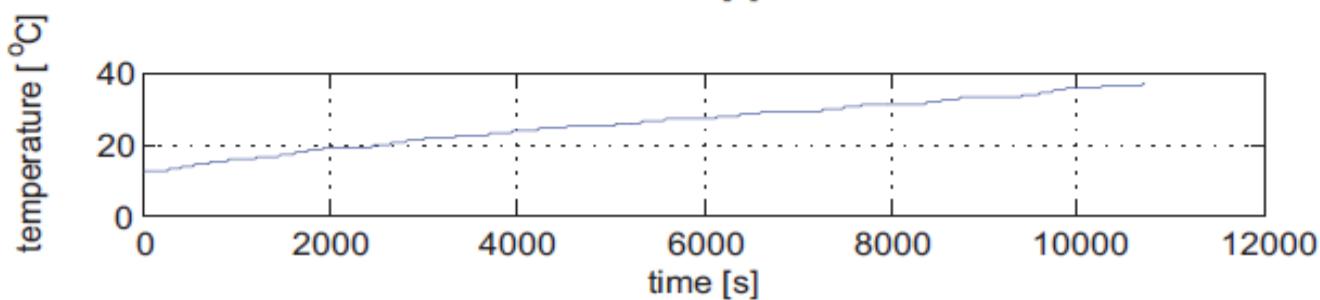


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Recommended current: 50A
Maximum current: 160A



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