



**CRISI RESEARCH CONSORTIUM FOR
INDUSTRY 4.0 SYSTEMS ENGINEERING**

A PHYSICAL MODEL THAT FITS

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Téo Taxi



200 electric vehicles

- No CO2 emission
- Nissan LEAF
- Renault Zoe
- Tesla Model S
- Tesla X

Technologies

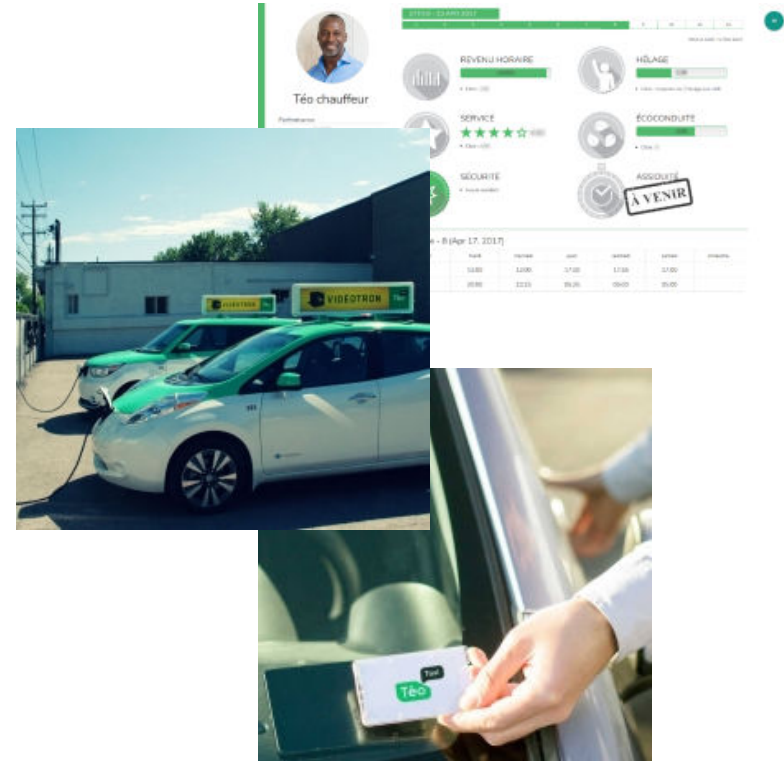
- Mobile application
- Consumption prediction algorithms



Limited vehicle range

○ Challenges:

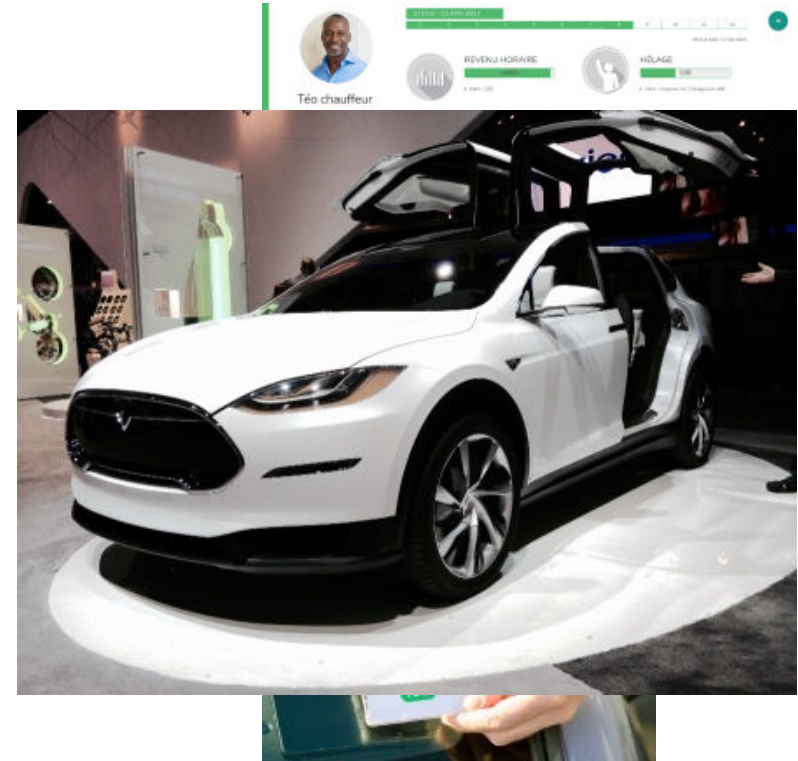
- Recharge planning
- Ride allocation
- Predicting charging time
- Predicting Energy Consumption



Limited vehicle range

○ Challenges:

- Recharge planning
- Ride allocation
- Predicting charging time
- **Predicting Energy Consumption**



Objectives

- Use a physical model to predict electric vehicle consumption and enhance its accuracy using historical data from Téo Taxi
- Allow better predictions for a new/unknown vehicle model



Basic Physical Model

$$E = \frac{1}{3600} \left(\overset{\text{Rolling resistance}}{mg(f \cos(\theta))} + \overset{\text{Potential Energy}}{\sin(\theta)} + \overset{\text{Aerodynamic}}{\frac{1}{2} \left(p C_x A \left(\frac{v}{3.6} \right)^2 \right)} + \overset{\text{Acceleration}}{m \frac{d_v}{d_t}} * d \right)$$

[De Cauwer et al., 2017]

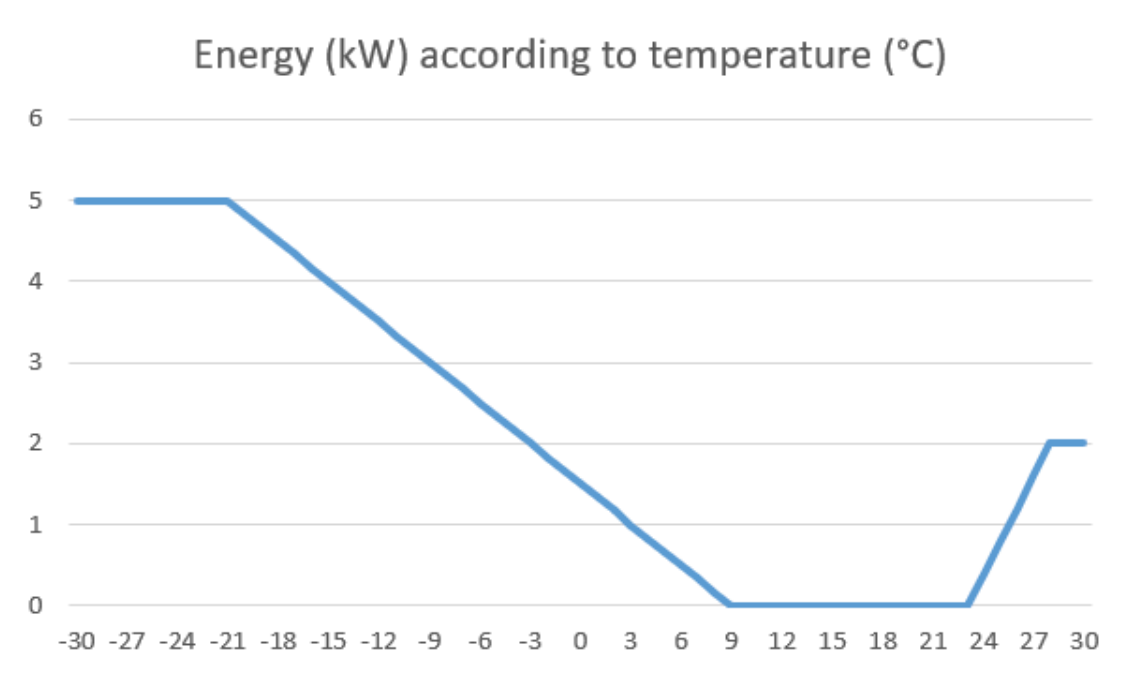


Extended Physical Model

$$E = \frac{1}{3600} \left(\underbrace{mg(f \cos(\theta))}_{\text{Rolling resistance}} + \underbrace{\sin(\theta)}_{\text{Potential Energy}} \right) + \underbrace{\frac{1}{2} \left(p C_x A \left(\frac{v}{3.6} \right)^2 \right)}_{\text{Aerodynamic}} + \underbrace{m \frac{d_v}{d_t}}_{\text{Acceleration}} * d \Bigg) + \underbrace{T}_{\text{Climate Control}} + \underbrace{A_c}_{\text{Accessories}}$$



Climate Control Term



Data

Taxi rides

Nissan LEAF (26 269)

Kia Soul EV (131 866)

Tesla Model S (22 082)

Tesla Model X (13 130)

Path



- Distance
- Elevation of the road

Driving



- Speed
- Duration
- Acceleration

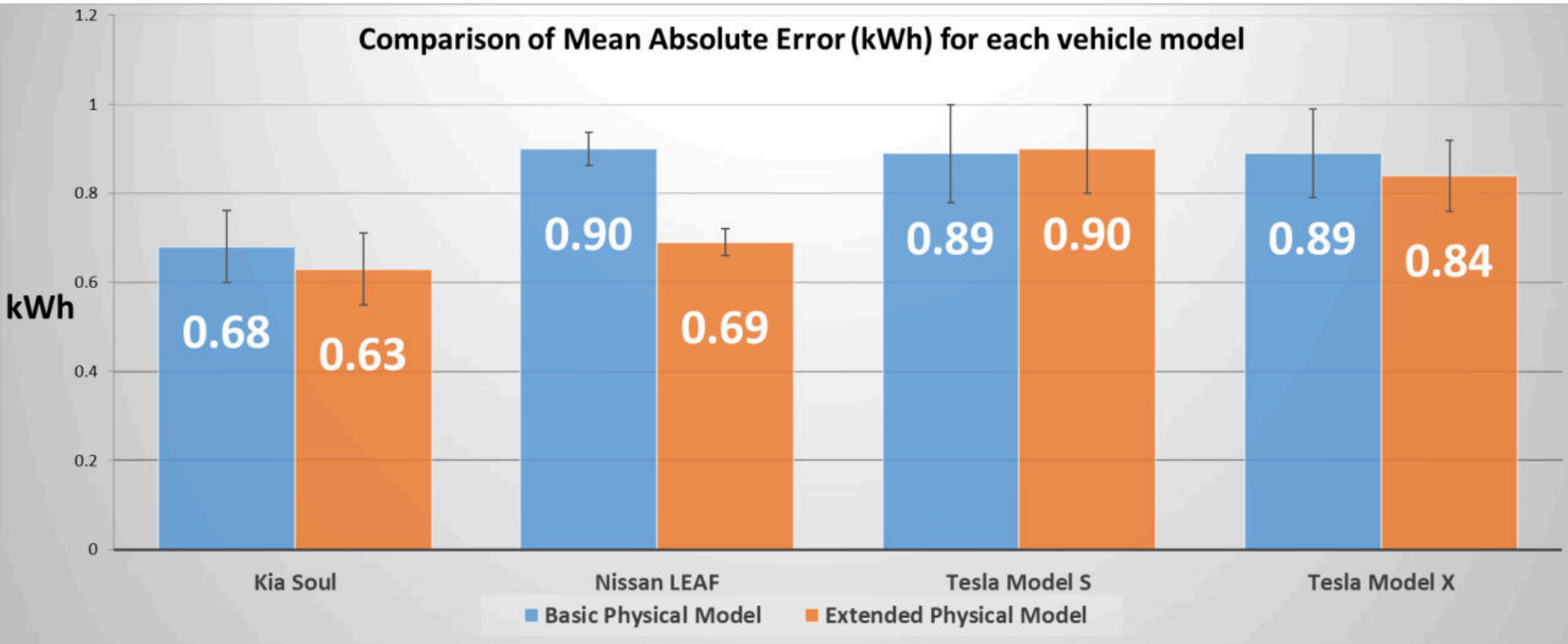
Weather



- Temperature



Comparing both models



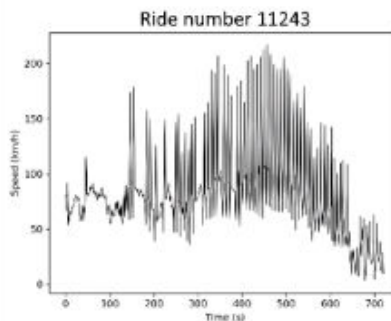
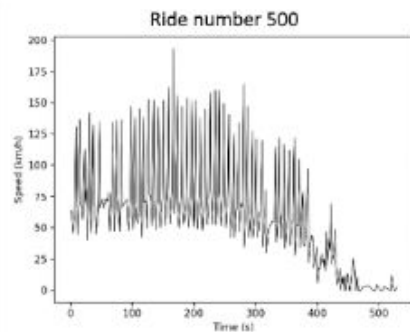
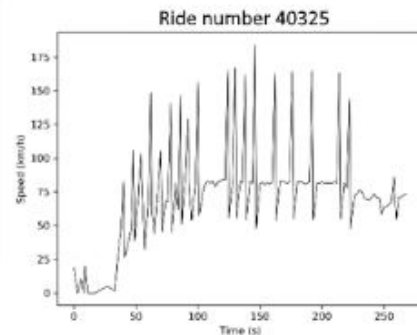
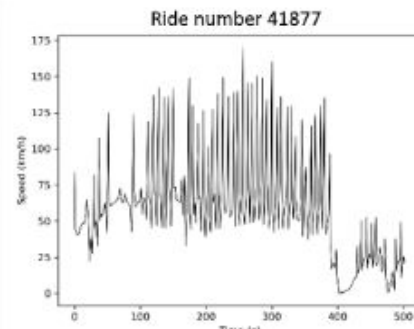
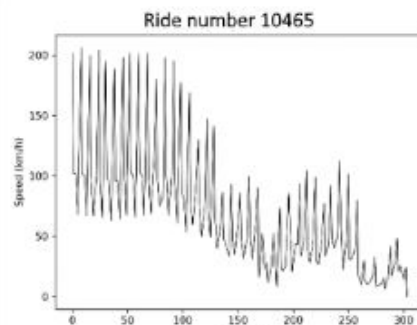
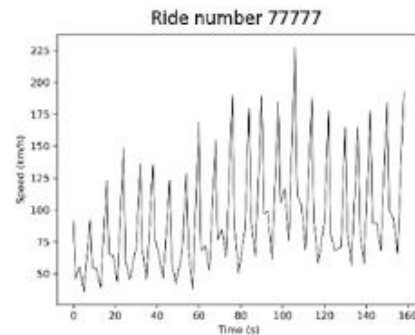
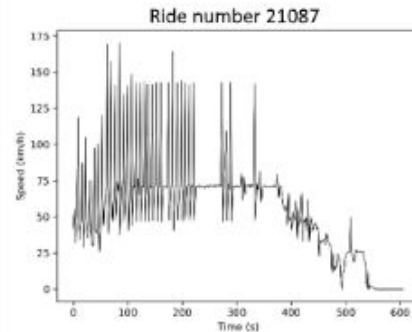
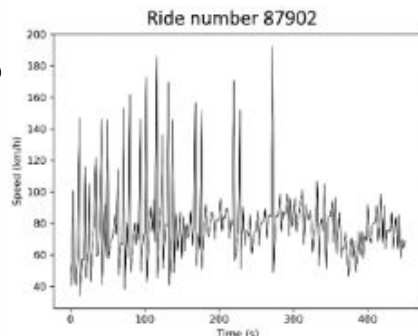
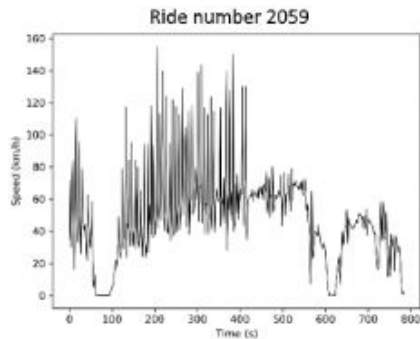
(Training on 80% of data and testing on 20% of data)

Fitted Extended Physical Model

$$E = \alpha_1 mg(f \cos(\theta) + \sin(\theta))d + \alpha_2 p C_x A \left(\frac{v}{3.6} \right)^2 d + \alpha_3 m \frac{d_v}{d_t} d + \alpha_4 T + \alpha_5 A_c$$



Speed issues



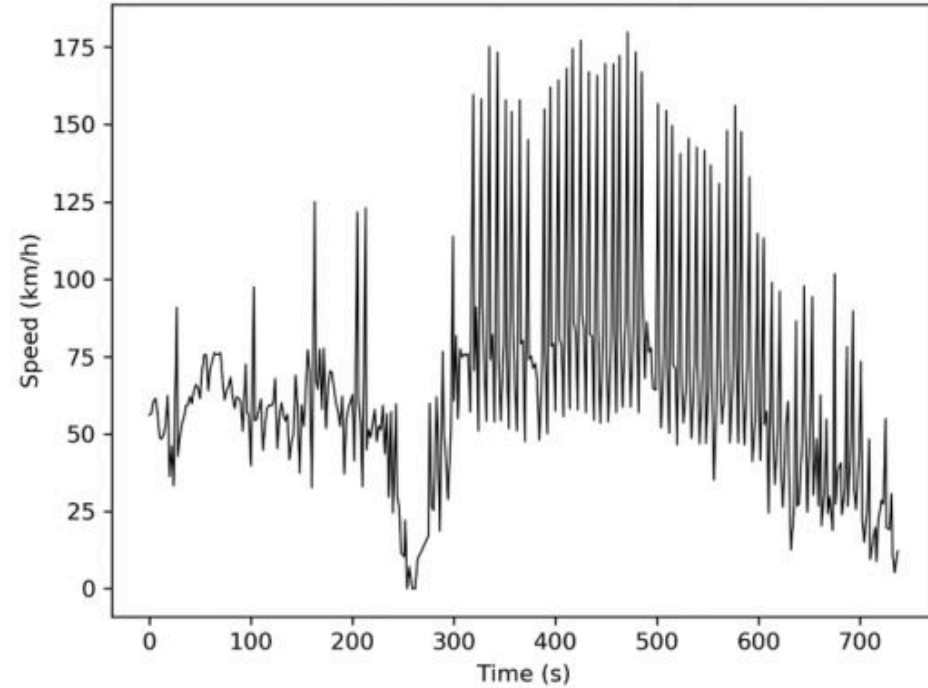
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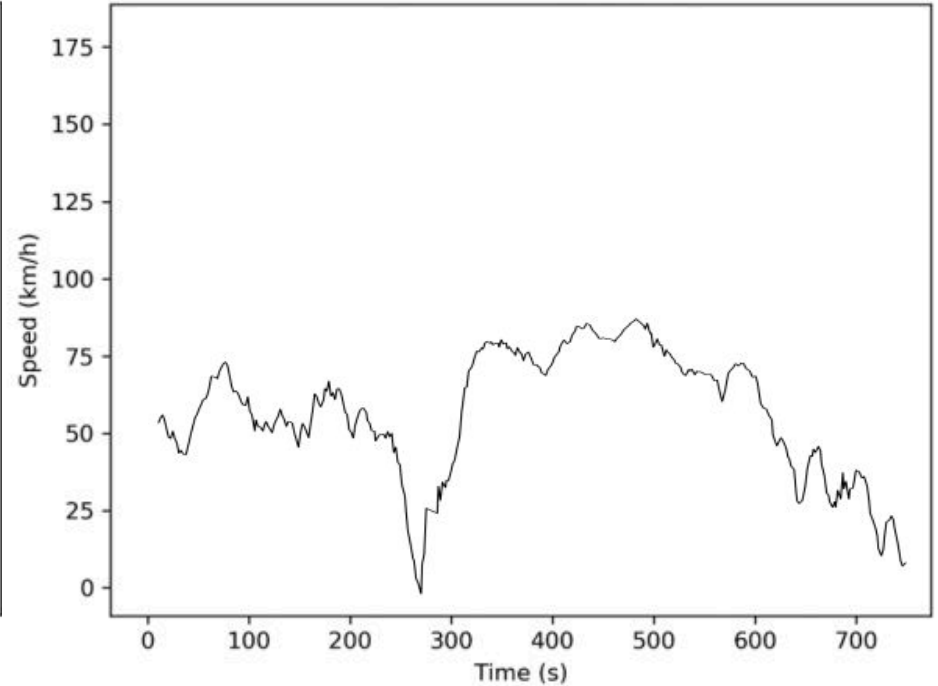
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Correcting speed issues

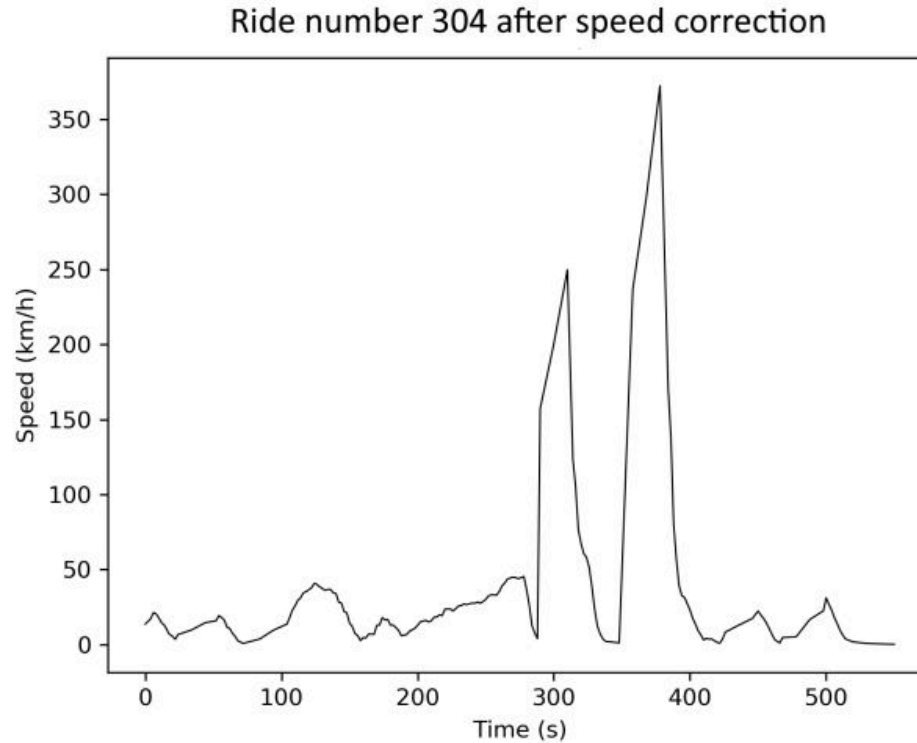
Ride number 208



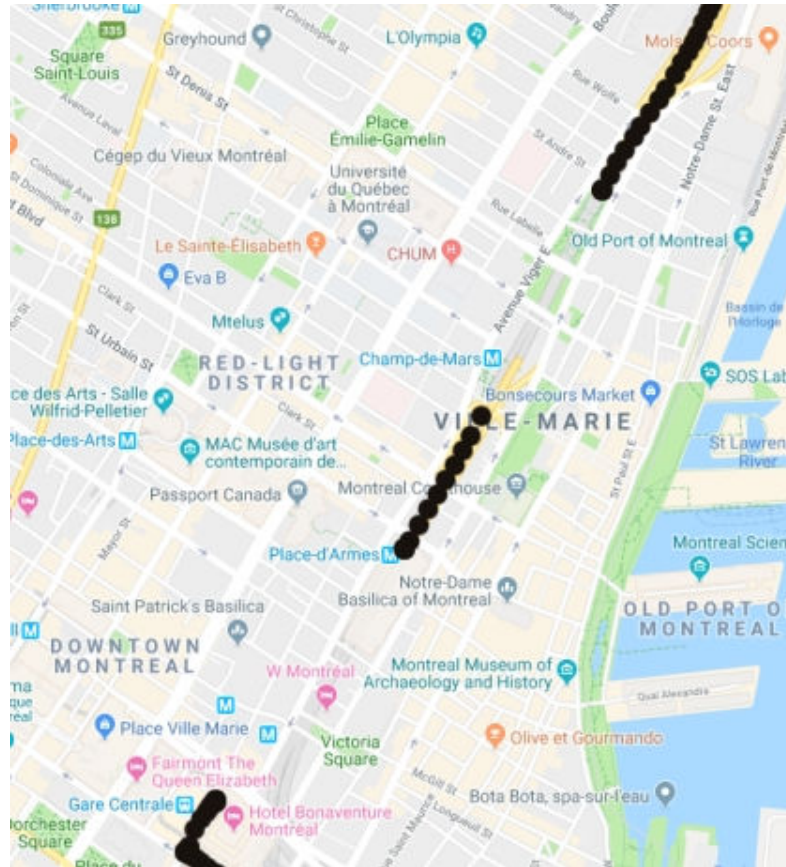
Ride number 208



Still some issues...



Teleportation

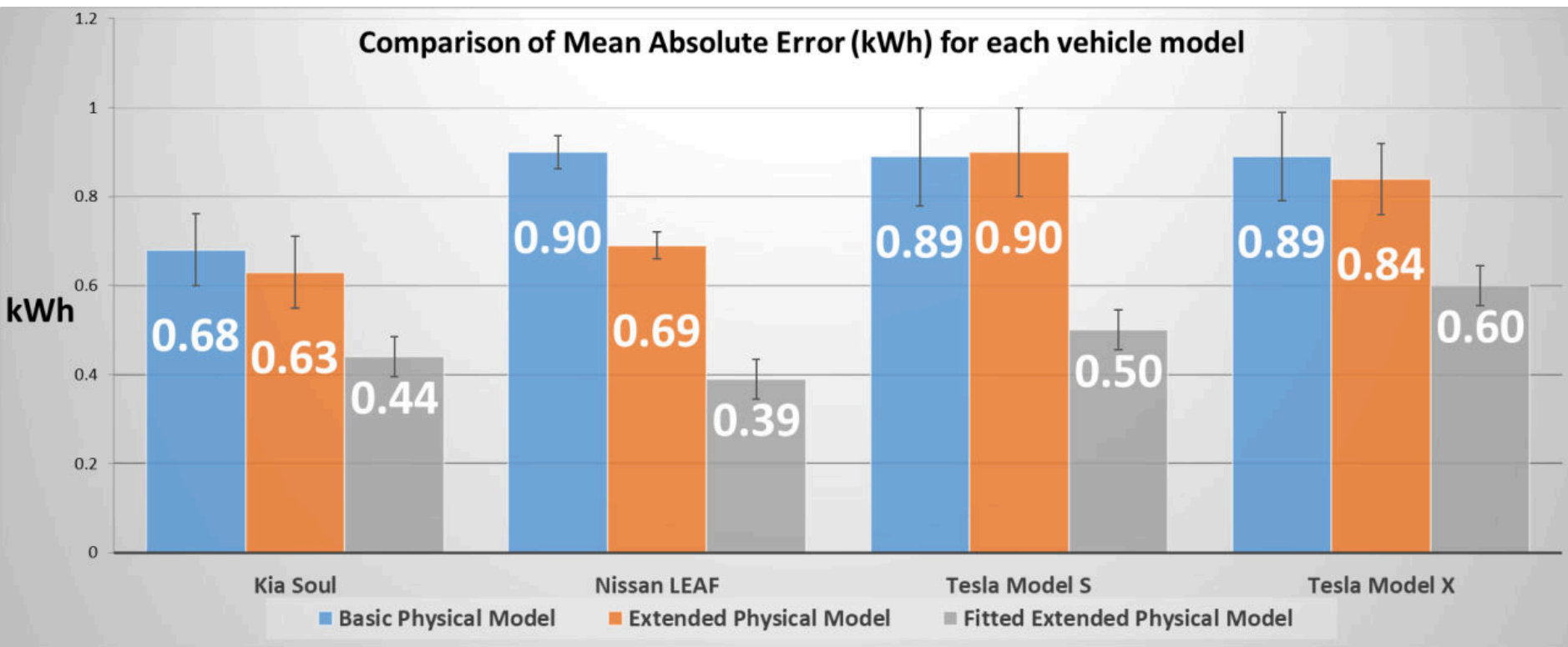


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Results



(Training on 80% of data and testing on 20% of data)

Approach for new vehicle

Training



Kia Soul EV



Nissan LEAF



Tesla Model S

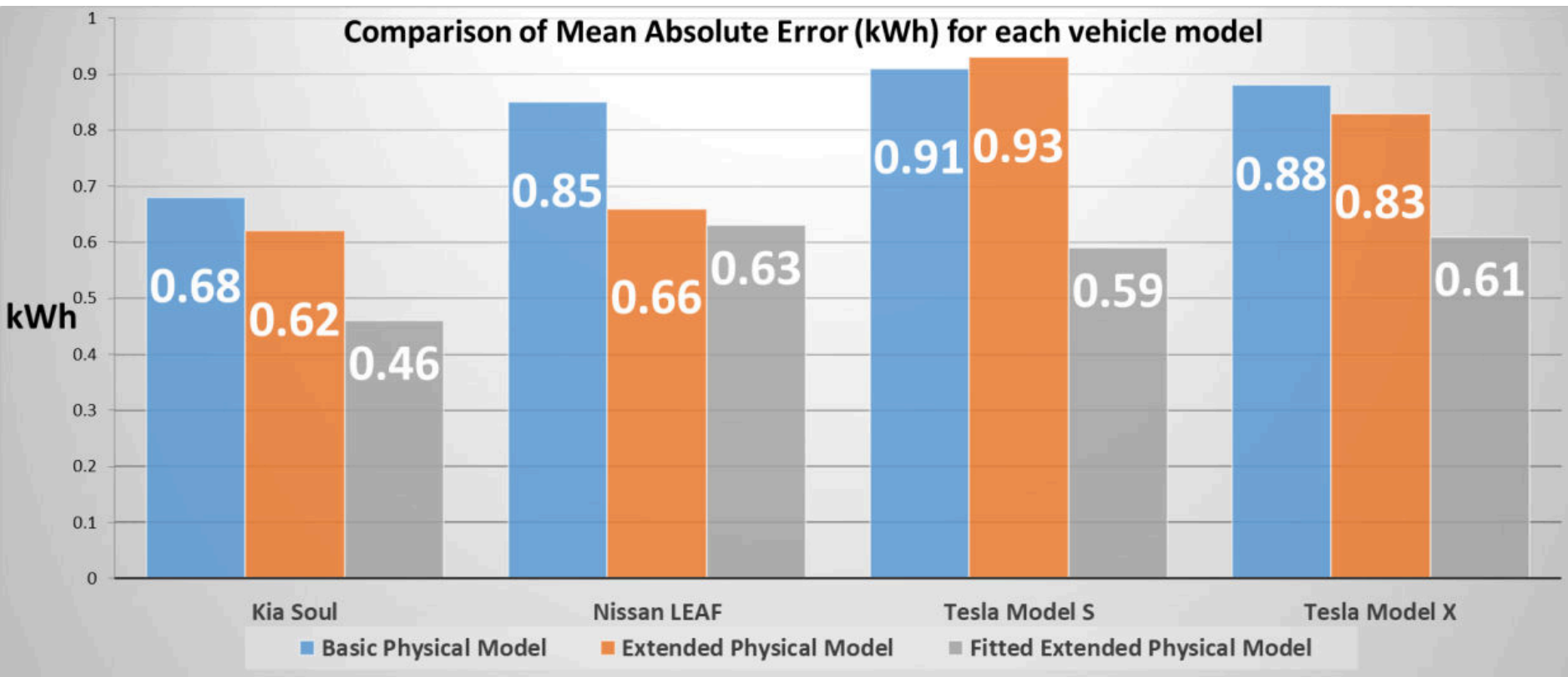


Tesla Model X

Testing



Results



Conclusion

- Improvement of as much as 44% (Tesla Model S)
- Data quality challenge
- Now exploring non-linear models (such as Neural Networks)

